





# SCIGATE AUTOMATION (S) PTE LTD

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Business Hours: Monday - Friday 8:30AM - 6:15PM

# More Precision

wireSENSOR // Draw-wire displacement sensors



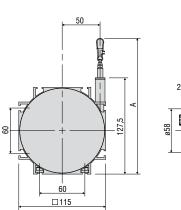
## Industrial draw-wire sensors

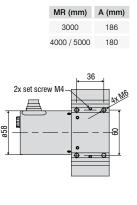
## wire SENSOR P115 analog

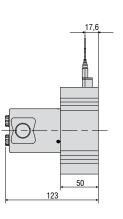


- Robust aluminium profile housing
- Customized versions for OEM
- Potentiometer, current and voltage output

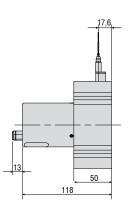
Model P115 (Measuring range 3000/4000/5000mm)





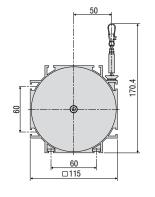


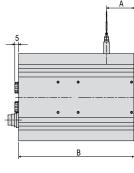
Output U/I

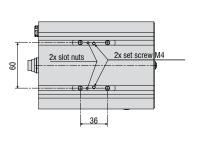


Output P

Model P115 (Measuring range 7500/10000/15000mm)







MR (mm)	A (mm)	B (mm)
7500	37	153
10000	44.5	198
15000	60.5	228

Model		WDS- 3000-P115	WDS- 4000-P115	WDS- 5000-P115	WDS- 7500-P115	WDS- 10000-P115	WDS- 15000-P115	
Measuring range		3000mm	4000mm	5000mm	7500mm	10000mm	15000mm	
Output		P, U, I						
Lingarity	<0.1% FSO	<3mm	-	-	-	-	-	
Linearity	<0.15% FSO	-	<6mm	<7.5mm	<11.3mm	<15mm	<22.5mm	
Resolution				quasi i	infinite			
Sensor element				hybrid pote	entiometer			
Temperature range				-20	+80 °C			
Material	housing			alumi	inium			
ivialeriai	draw wire	coated poly	amid stainless steel	(ø 0.45mm)	coated poly	vamid stainless stee	l (ø 1.0mm)	
Sensor mounting				slot	nut			
Wire mounting				wire	clip			
Wire acceleration				аррі	r. 6g			
Wire retraction force (min)		4.5N	4N	4N	8N	8N	8N	
Wire extension force (max)		8N	8.5N	9N	24N	21N	25N	
Protection class				IP 65 (only if	connected)			
Vibration		20g, 20Hz - 2kHz						
Mechanical shock		50g, 20ms						
Electrical connection	Р			integrated ca	ble, axial, 1m			
Electrical conflection	U, I	flange connector, radial, 8-pin, DIN45326						
Weight			appr. 1.1kg		2.2kg	3.2kg	3.5kg	

FSO = Full Scale Output Specifications for analog outputs on page 51.

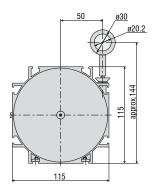
## Article description

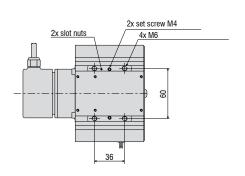
DS -	3000 -	P115 -	CA -	Р		
				P: pote U: volta I: curre	ige	connection CA: P115-3000/4000/5000 connection SA: P115-7500/10000/15000 connection SR: P115-3000/4000/5000 connection SA: P115-7500/10000/15000 connection SR: P115-3000/4000/5000 connection SA: P115-7500/10000/15000
			Connect SR: rad SA: axia CA: inte	lial plug al plug	able, axial,	1m
		Model P	115			
	Measur	ing range i	n mm			

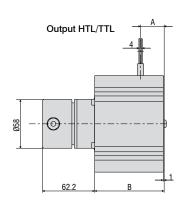


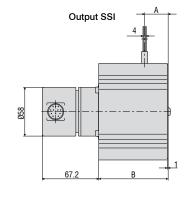
- Robust aluminium profile housing
- Customized versions for OEM
- Incremental/absolute encoder

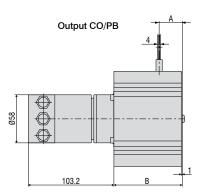
#### Model P115











MR (mm)	A (mm)	B (mm)
5000	28	82.5
7500	37	105.5
10000	44.5	148.5
15000	61	180.5

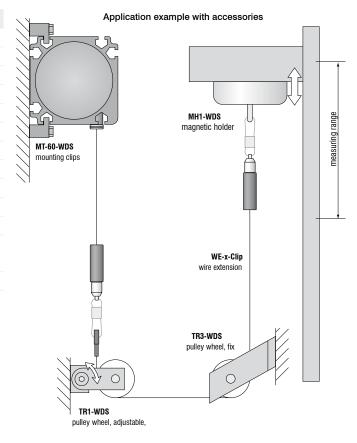
Model		WDS-5000-P115	WDS-7500-P115	WDS-10000-P115	WDS-15000-P115		
Measuring range		5000mm	7500mm	10000mm	15000mm		
Output		HTL, TTL, SSI, PB, CO					
Linearity	<0.01% FSO	-	-	<1mm	<1.5mm		
Linearity	<0.02% FSO	<1mm	<1.5mm	-	-		
Resolution	HTL, TTL		0.105mm (9.5	2 pulses/mm)			
nesolution	SSI, PB, CO		0.038	Bmm			
Sensor element			incremental/ab	solute encoder			
Temperature range			-20 ·	+80°C			
Material	housing	aluminium					
draw wire		coated polyamid stainless steel (ø 1.0mm)					
Sensor mounting		slot nuts					
Wire mounting		eyelet					
Wire acceleration		5g	6g	3g	<b>3</b> g		
Wire retraction force (min)		4N	8N	8N	8N		
Wire extension force (max)		16N	24N	21N	25N		
Protection class			IP 65 (only if	connected)			
Vibration			20g, 20H	lz - 2kHz			
Mechanical shock		50g, 10ms					
	HTL, TTL	integrated cable, radial, 1m					
Electrical connection	SSI	flange connector, radial,12-pin					
	PB, CO	3, CO bus cover					
Weight		appr. 2kg	appr. 2.5kg	appr. 3.5kg	appr. 4.5kg		

FSO = Full Scale Output Specifications for digital outputs on page 52.

## Article description

DS -	5000 -	P115 -	CR -	TTL	
				Output HTL TTL CO: CA PB: Pro SSI	
			CR (Ou	tput SSI): tput HTL,	radial plug TTL): integrated cable, radial, 1m PB): bus cover
		Model P	115		
	Measuri	ing range i	n mm		

Accessories:	
WE-xxx-M4	Wire extension with M4-wire connection, x=length
WE-xxxx-Clip	Wire extension with eyelet, x=length
TR1-WDS	Pulley wheel, adjustable
TR3-WDS	Pulley wheel, fixed
GK1-WDS	Attachment head for M4
MH1-WDS	Magnetic holder for wire mounting
MH2-WDS	Magnetic holder for sensor mounting
MT-60-WDS	Mounting clamp for WDS-P60
FC8	Female connector for WDS, 8-pin
FC8/90	Female connector 90° for WDS
PC 3/8-WDS	Sensor cable, lenght 3m
PS 2020	(Power Supply 24 V / 2,5 A, Input 100 - 240 VAC, output 24 VDC / 2.5 A, for snap in mounting on DIN 50022 rail)
WDS-MP60	Mounting plate for P60 sensors

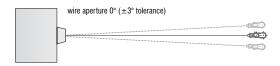


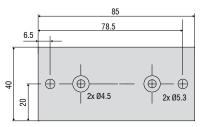
## Installation information:

Wire attachment: The free return of the measurement wire is not permissible and it is essential that this is avoided during installation.

#### Wire exit angle:

When mounting a draw-wire displacement sensor, a straight wire exit ( $\pm 3^{\circ}$  tolerance) must be taken into account. If this tolerance is exceeded, increased material wear on the wire and at the wire aperture must be expected.





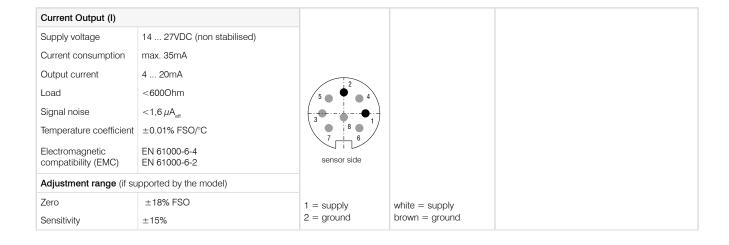
Mounting plate WDS-MP60

## Output specifications analog

Output	Plug M16 -SA / -SR	Integrated cable -CA / -CR	Open contacts
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Potentiometric output (P) max. 32VDC at 1kOhm / 1 Wmax Supply voltage Resistance 1kOhm ±10% (potentiometer) Temperature coefficient ±0.0025% FSO/°C sensor side 1 = input +white = input +1 = input +2 = groundbrown = ground2 = signal ccw 1 - \ \ \ \ \ \ \ \ \ \ \ \ - 3 cw 3 = signal green = signal 3 = ground

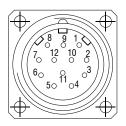
Voltage output (U) 14 ... 27VDC (non stabilised) Supply voltage Current consumption max. 30mA 0 ... 10VDC Output voltage Option 0 ... 5 / ±5V Load impedance >5kOhm Signal noise  $0.5 \mathrm{mV}_{\mathrm{eff}}$ sensor side Temperature coefficient ±0.005% FSO/°C Electromagnetic EN 61000-6-4 compatibility (EMC) EN 61000-6-2 Adjustment ranges (if supported by the model) 1 = supply $\quad \text{white} = \text{supply} \quad$ 2 = groundbrown = ground Zero ±20% FSO 3 = signal green = signal yellow = groundSensitivity ±20% 4 = ground



## Output specifications SSI

1 UB	Encoder power supply connection
2 GND	Encoder ground connection. The voltage drawn to GND is UB.
3 Pulses +	Positive SSI pulse input. Pulse + forms a current loop with pulse A current of approx. 7 mA in direction of pulse + input generates a logical 1 in positive logic.
4 Data +	Positive, serial data output of the differential line driver. A High level at the output corresponds to logical 1 in positive logic.
5 ZERO	Zero setting input for setting a zero point at any desired point within the entire resolution. The zeroing process is triggered by a High pulse (pulse duration ≥ 100 ms) and must take place after the rotating direction selection (UP/DOWN). For maximum interference immunity, the input must be connected to GND after zeroing.
6 Data -	Negative, serial data output of the differential line driver. A High level at the output corresponds to logical 0 in positive logic.
7 Pulses -	Negative SSI pulse input. Pulse - forms a current loop with pulse +. A current of approx. 7 mA in direction of pulse - input generates a logical 0 in positive logic.
8 / 10 DATAVALID DATAVALID MT	Diagnosis outputs DV and DV MT Jumps in data word, e.g. due to defective LED or photoreceiver, are displayed via the DV output. In addition, the power supply of the multiturn sensor unit is monitored and the DV MT output is set when a specified voltage level is dropped below. Both outputs are Low-active, i.e. are switched through to GND in the case of an error.
9 UP/DOWN	UP/DOWN counting direction input. When not connected, this input is on High. UP/ DOWN-High means increasing output data with a clockwise shaft rotating direction when looking at the flange. UP/ DOWN-Low means increasing values with a counter-clockwise shaft rotating direction when looking at the flange.
11 / 12	Not in use

Pin assignment					
Pin	Cable color	Assignment			
1	brown	UB			
2	black	GND			
3	blue	Pulses +			
4	beige	Data +			
5	green	ZERO			
6	yellow	Data -			
7	violet	Pulses -			
8	brown/yellow	DATAVALID			
9	pink	UP/ DOWN			
10	black/yellow	DATAVALID MT			
11	-	-			
12	-	-			



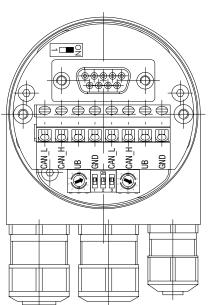
Please use leads twisted in pairs for extension cables.

Inputs					
Control signals UP/DOWN and	d Zero				
Level High	> 0.7 UB				
Level Low	< 0.3 UB				
Connection:	UP/DOWN input with 10kohms to UB, zeroing input with 10kohms to GND.				
SSI pulse					
Optocoupler inputs for electrical isolation					

Outputs				
SSI data	RS485 driver			
Diagnostic outputs				
Push-pull outputs are short-circuit-pr	oof			
Level High	> UB -3.5V	(with $I = -20mA$ )		
Level Low	≤ 0.5V	(with I = 20mA)		

## Output specifications CANopen

CANopen features		
Bus protocol	CANopen	
Device profile	CANopen - CiA DSP 406, V 3.0	
CANopen Features	Device Class 2, CAN 2.0B	
Operating modes (with SDO progr.)	Polling Mode (asynch, via SDO)  Cyclic Mode (asynch-cyclic) The encoder cyclically sends the current process actual value without a request by a master. The cycle time can be parameterized for values between 1 and 65535 ms. Synch Mode (synch-cyclic)  The encoder sends the current actual process value after receiving a synch telegram sent by a master. The synch counter in the encoder can be parameterized so that the position value is not sent until after a defined number of synch telegrams.  Acyclic Mode (synch-acyclic)	
Preset value	With the "Preset" parameter the encoder can be set to a desired actual process value that corresponds to the defined axis position of the system. The offset value between the encoder zero point and the mechanical zero point of the system is saved in the encoder.	
Rotating direction	With the operating parameter the rotating direction in which the output code is to increase or decrease can be parameterized. Scaling The steps per revolution and the total revolution can be parameterized.	
Scaling	The steps per revolution and the total revolution can be parameterized.	
Diagnose	The encoder supports the following error messages: - Position and parameter error - Lithium cell voltage at lower limit (Multiturn)	
Default setting	50kbit/s, node number 1	



Setting of terminating Resistor for CANopen



ON = Last user OFF = User X

Setting CANopen baud rate			
Baud rate		Setting Dip Switch	
Daud Tale	1	2	3
10kBit/s	OFF	OFF	OFF
20kBit/s	OFF	OFF	ON
50kBit/s	OFF	ON	OFF
125kBit/s	OFF	ON	ON
250kBit/s	ON	OFF	OFF
500kBit/s	ON	OFF	ON
800kBit/s	ON	ON	OFF
1MBit/s	ON	ON	ON

Contact description CANopen		
CAN_L	CAN Bus Signal (dominant Low)	
CAN_H	CAN Bus Signal (dominant High)	
UB	Supply voltage 1030VDC	
GND	Ground contact for UB	
	(Terminals with the same designation are internally interconnected)	

## Settings of user address for CANopen

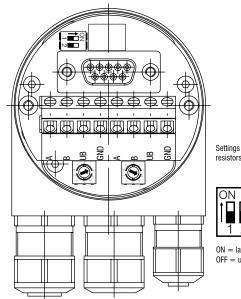
Address can be set with rotary switch. Example: User address 23





## Output specifications Profibus

Profibus-DP features	
Bus protocol	Profibus-DP
Profibus features	Device Class 1 and 2
Data exch. functions	Input: Position value Additional parameterized speed signal (readout of the current rotary speed) Output: Preset value
Preset value	With the "Preset" parameter the encoder can be set to a desired actual value that corresponds to the defined axis position of the system.
Parameter functions	Rotating direction: With the operating parameter the rotating direction for which the output code is to increase or decrease can be parameterized.
Diagnose	The encoder supports the following error messages: - Position error - Lithium cell voltage at lower limit (Multiturn)
Default setting	User address 00



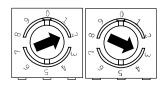
Settings of terminating resistors for Profibus-DP



ON = last user OFF = user X

## Settings of user address for Profibus-DP

Settings of user address for Profibus-DP



## Contact description Profibus-DP

A Negative serial data line

B Positive serial data line

UB Supply voltage 10...30VDC

GND Ground contact for UB

(Terminals with the same designation are internally interconnected)

# 

Output TTL	Linedriver (5 VDC)	
Level High	≥ 2.5V	(with $I = -20mA$ )
Pegel Low	≤ 0.5V	(with $I = 20mA$ )
Load High	≤ 20mA	
Output	$A, \overline{A}, B, \overline{B}, 0$	

Output TTL01	NPN (5 VDC ±5%)
Level High	≥ UB -0.2V
Level Low	0,55 - 0.75V
Load High	≤ 1.85mA
Output	A, B, 0

Output TTL02	Linedriver (5 VDC	±5 %)
Level High	≥ 2.0V	(with I= -40mA)
Level Low	≤ 0.5V	(with I= 40mA)
Load High	≤ 40mA	
Output	$A, \overline{A}, B, \overline{B}, 0$	

Output HTL	Push-pull (10 30	VDC)
Level High	≥ UB -3V	(with $I = -20mA$ )
Level Low	≤ 1.5V	(with $I = 20mA$ )
Load High	≤ 40mA	
Output	$A, \overline{A}, B, \overline{B}, 0$	

Output E	Push-pull ((5 VDC)
Level High	≥ UB -2.5V
Level Low	≤ 0.5V
Load High	≤ 50mA
Output	A, B, 0
Output E830	Push-pull ((8 30 VDC)
Level High	≥ UB -3V
Level Low	≤ 2.5V

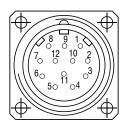
 $\leq$  50mA

A, B, 0

Load High

Output

Pin assignment TTL, HTL		
Pin	Cable color	Assignment
Pin 1	pink	B inv.
Pin 2	blue	UB Sense
Pin 3	red	N (zero impulse)
Pin 4	black	N inv. (zero impulse inv.)
Pin 5	brown	Α
Pin 6	green	A inv.
Pin 7	-	-
Pin 8	grey	В
Pin 9	-	-
Pin 10	white/green	GND
Pin 11	white	GND Sense
Pin 12	brown/green	UB



Pin 2 and Pin 12 are internally connected as well as Pin 11 and 10.

For cable length > 10m twisted pair wires are required.

Connection assignment E, E830		
Cable color	Assignment	
white	OV	
brown	+UB	
green	A	
-	Ā	
yellow	В	
-	B	
grey	0	

Connection assignment TTL01		
Cable color	Assignment	
brown	0V	
grey	+UB	
white	A	
green	В	
yellow	0	

Connection assignment TTL02	
Cable color	Assignment
red	+UB
black	OV
brown	Α
black	Ā
orange	В
black	B
yellow	0
black	n.c.

## High performance sensors made by Micro-Epsilon



Sensors and systems for displacement and position



Sensors and measurement devices for non-contact temperature measurement



2D/3D profile sensors (laser scanner)



Optical micrometers, fibre optic sensors and fibre optics



Color recognition sensors, LED analyzers and color inline spectrometer



Measurement and inspection systems