



More Precision

scanCONTROL // 2D/3D laser scanner (laser profile sensors)



Modbus
RS422
GIGE VISION
digital
analog
Ethernet UDP

EtherNet/IP™
PROFINET®

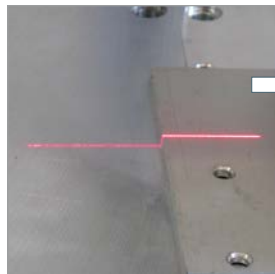
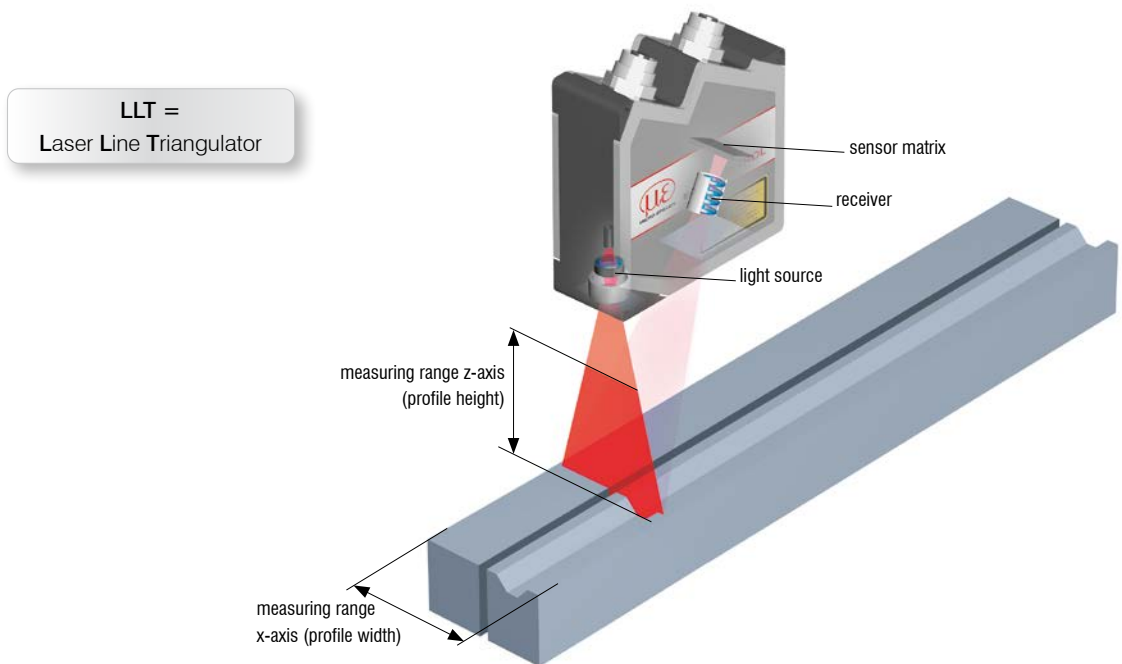
EtherCAT®

NEW**scanCONTROL Gateway** (page 18)

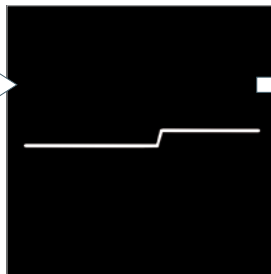
- Outputs measured values via PROFINET, EtherCAT and EtherNet/IP
- Up to 4 sensors

**NEW****SMART PLC Unit** (page 30)

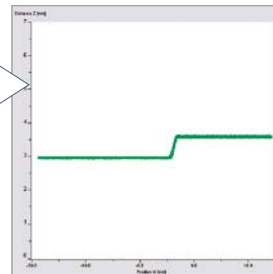
- Evaluates measured values of SMART and GAP sensors
- Fast data processing



Laser line
Projecting a laser line onto the target surface



Sensor matrix (pixels)
The diffusely reflected light from the laser line is shown on the high quality sensor matrix



Calibrated x/z measuring points
Calculation of the distance coordinate z and the actual position x along the laser line for each measuring point

What are laser scanners?

Laser scanners from the LLT series record, measure and evaluate profiles on a variety of different target surfaces. With its scanCONTROL/gapCONTROL series, Micro-Epsilon offers from the pre-configured sensors to the complex measuring systems all from a single source.

The measuring principle



Laser scanners - often referred to as profile sensors - use the laser triangulation principle for two-dimensional profile detection on different target surfaces. By using special lenses, a laser beam is enlarged to form a static laser line and is projected onto the target surface. The optical system projects the diffusely reflected light of this laser line onto a highly sensitive sensor matrix. In addition to distance information (z-axis), the controller also uses this camera image to calculate the position along the laser line (x-axis). These measured values are then output in a two-dimensional coordinate system that is fixed with respect to the sensor. In the case of moving objects or a traversing sensor, it is therefore possible to obtain 3D measurement values.

Customer evaluation

These models provide calibrated profile data which can be further processed on a PC using a customer software evaluation.

Integrated evaluation

These models provide selected measurement values. The parameter set up for the sensors and the measurement programs is stored in the integrated controller.

	COMPACT	HIGHSPEED	SMART	GAP
	Laser scanners for common measurement tasks	Laser scanners with fast profile frequency	Laser scanners with comprehensive software	Laser scanners with software specifically developed for gap measurements
 <p>LLT26xx 640 points/profile Profile frequency Standard up to 300Hz High speed up to 4000Hz</p>	<p>scanCONTROL 2600 ▶ Page 10</p>	<p>scanCONTROL 2650 ▶ Page 10</p>	<p>scanCONTROL 2610 ▶ Page 10</p>	<p>gapCONTROL 2611 ▶ Page 10</p>
 <p>LLT29xx 1280 points/profile Profile frequency Standard up to 300Hz High speed up to 2000Hz Available with red or blue diode</p>	<p>scanCONTROL 2900 ▶ Page 12</p>	<p>scanCONTROL 2950 ▶ Page 12</p>	<p>scanCONTROL 2910 ▶ Page 12</p>	<p>gapCONTROL 2911 ▶ Page 12</p>
	<p>Integration: SDK for C/ C++, LabVIEW-VI and examples for C# and Linux ▶ Page 28</p>		<p>Evaluation: scanCONTROL Configuration Tools ▶ Page 22</p>	<p>Evaluation: gapCONTROL Setup Software ▶ Page 24</p>

Transmission of **calibrated profile data**

COMPACT

The COMPACT sensors are used for providing calibrated profile data for external profile analysis, for example, on a PC. They are suitable for static and dynamic measurements.

An Ethernet interface allows the user to configure the sensor via a PC application, as well as to transmit profile data. More details about the software interface can be found in the "Integrating scanCONTROL in application software" chapter.

HIGHSPEED

The HIGHSPEED models are also used to transmit the calibrated profile data. With a profile frequency of up to 4000Hz, these sensors offer everything for advanced high speed and 3D applications.

Parameter set up via customer software application



Individual further processing of calibrated profile data

Measurement data output

SMART

The scanCONTROL SMART series offers plug & play solutions for simple-to-complex measurement tasks, eliminating the need for any external controller or PC.

Set up and configuration of the sensor is carried out via the scanCONTROL Configuration Tools PC software, which enables the measurement of steps, angles, seams and grooves. The parameter sets are stored in the sensor which is why the sensor autonomously performs measurements without requiring any external control devices or PCs.

GAP

The GAP class offers a plug & play solution especially for gap measurements. The gapCONTROL Setup Software enables the necessary set up and configuration for different gap types and to store them in the sensor.

Parameter set up via scanCONTROL Configuration Tools / gapCONTROL Setup Software



Profile analysis in the sensor head, transmission of measured values

Advanced technology

- Up to 1280 points per profile
- Measurement frequency up to 4000 profiles/sec.
- Compact size
- Integrated evaluation without any external controller or IPC
- Factory calibration for metals
- Made / Developed in Germany
- Numerous references worldwide
- Proven high operational safety in the 24/7 operation over many years
- Real Time Surface Compensation

Different laser types

- 2M class (red)
- 3B class (red)
- Blue Laser



Universal application

- Inline measurement of gap, profile, step, angle, ...
- Provides 3D information and images for image processing
- Profile transmission or measurement data output
- Robust: for use in processing lines and laboratories
- Also suitable for use with robotic applications
- Multi scanner applications
- Versions for integrators and end users



Interfaces

- Gigabit Ethernet (GigE Vision)
- Trigger and encoder input
- Gateway for PROFINET, EtherNet/IP and EtherCAT
- Output Unit for analog outputs and switch signals
- Power over Ethernet (PoE) - only one cable
- Secure measurement data output via Modbus
- Fast measurement data output via UDP
- Direct communication using PLC

Comprehensive software

- SMART and GAP classes:
 - Analysis and evaluation directly in the sensor head
- Configuration software provides ease of use
- Libraries for C, C++, C#
- LabVIEW driver
- Linux implementation
- Free software, libraries and firmware updates

Real Time Surface Compensation: Dynamic adaption to rapidly changing surfaces

Laser profile scanners use the diffusely reflected laser light. The intensity of reflection is (highly) dependent on the surface properties like color, shininess and light absorption of the measurement target.

The Real Time Surface Compensation feature of the sensors permits reliable measurements of constantly changing surface conditions. Real time adaption of exposure time and the threshold of reflection detection enable you to get stable measurement results in fast-changing measurement situations without having to adapt the sensor settings manually.

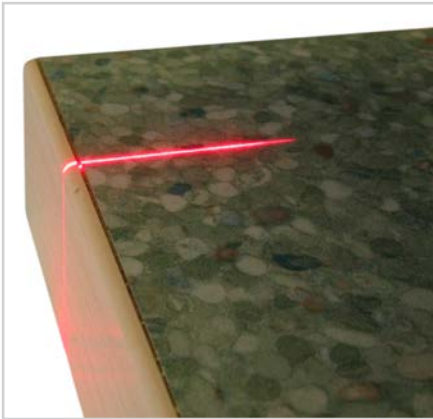


scanCONTROL / gapCONTROL

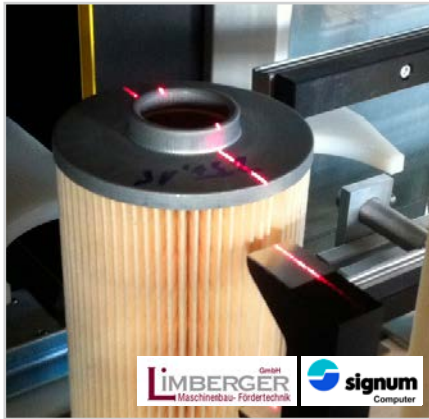
Sensor, solution and system from a single source

Micro-Epsilon has many years' experience in integrating highly efficient laser line sensors to customer applications and in supplying complete systems from a single source.

LLT sensors are adapted to a variety of common applications in quality control, production processes and automation.



Defect recognition on worktops



Filter height in the automotive industry



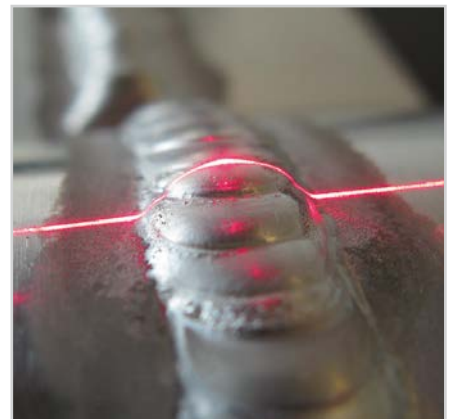
V-gap measurement on pipes



Gap measurement on a car body



Profile measurements on brake disks



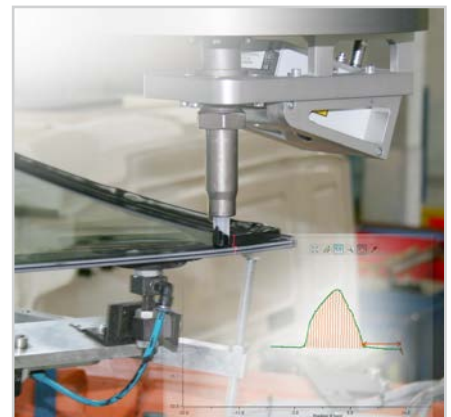
Measuring weld seam profiles



Tyre inspection



Distance measurement at the centre console



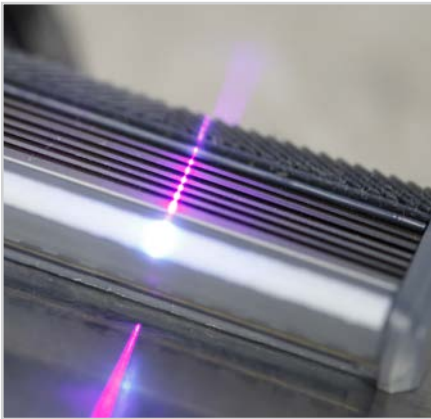
Inspection of the adhesive beading

scanCONTROL / gapCONTROL BL

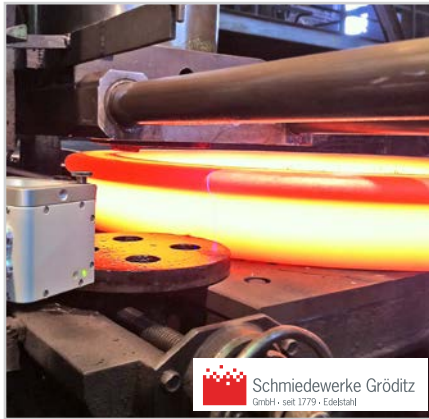
The laser scanners with blue laser line are used for multi-dimensional measurement on red-hot glowing metals as well as on transparent and organic materials. While allowing higher stability, the blue laser light does not

penetrate the measurement object due to the shorter wavelength of the blue-violet laser. Compared to red lasers, blue laser sensors enable more reliable measurements on red-hot glowing and organic objects.

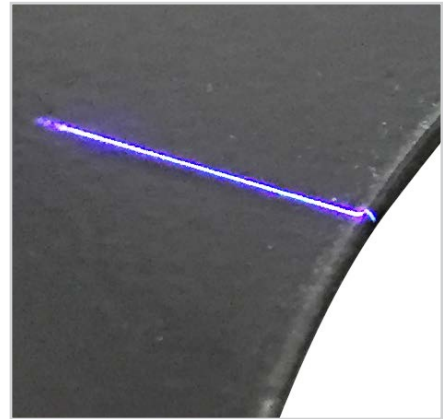
The high-focused, blue laser line enables furthermore to use laser scanners with 10mm line length in highest precision.



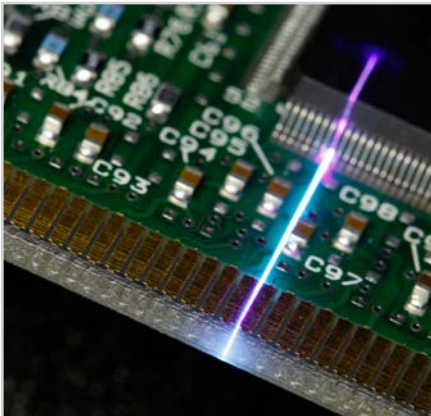
Blade angle of razors



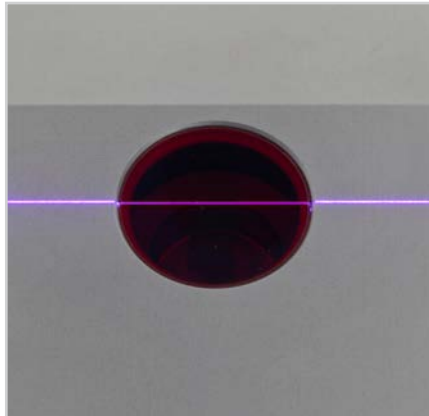
Production of steel-forged rings



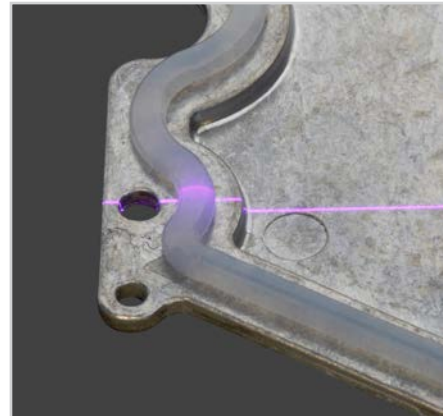
Burr measurement on punching sheets



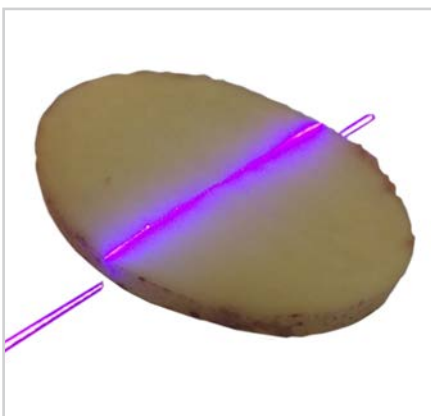
Position of electronic components



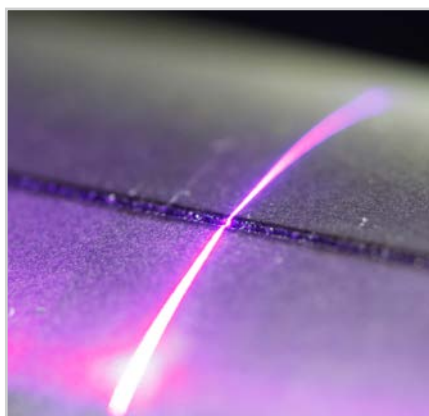
Gap measurement of inserted glass



Inspection of silicone adhesive beading



Thickness measurement of potato slices



Completeness of laser welding seams



Thermal tests



- z-axis measuring range up to 265mm
- x-axis measuring range up to 143.5mm
- Profile frequency up to 4,000Hz
- Measuring rate up to 2,560,000 points/sec
- z-axis reference resolution from 2µm
- Resolution x-axis up to 640 points

Compact design suitable for all measurement tasks

The design of the LLT 26xx series is focussed on compact size and low weight. The controller is integrated in the housing, simplifying cabling arrangements and mechanical integration. Due to its compact design and the profile frequency of up to 4000 profiles/sec., the 26xx series is especially suitable for dynamic and robotic applications.

Interfaces for universal integration

The multi-function port can be used for power supply, as data output, for switching parameters, as trigger input or for synchronizing several scanCONTROL sensors. During synchronous operation, an integrated mode can be used to operate the sensors alternately compensating for overlapping laser lines. One scanner is measuring whilst the other laser line is switched off.




The scanners can be supplied via Ethernet if necessary. If Industrial Ethernet is used as data output, only one cable will remain that connects the sensor to the periphery.

For all SMART and GAP class sensors, the measurement data output can be carried out in different ways, e.g. via Ethernet UDP, Modbus TCP or serial. Micro-Epsilon converters enable data transmission via analog signals, digital switching signals, PROFINET, Ethernet/IP or EtherCAT.

Article description structure

LLT	26	00	-25	/SI
<p>Options /SI = integrated laser switch-off /PT = integrated pigtail cable 0.25 m /3B = 3B laser class</p>				
<p>Measuring range 25mm 50mm 100mm</p>				
<p>Class 00=COMPACT 10=SMART 11=GAP 50=HIGHSPEED</p>				
<p>Series LLT26xx</p>				

Options*

/SI	Integrated laser switch-off	/PT	Pigtail cable
	Hardware switch-off of the laser line		0.25m long cable directly out of the sensor
	3B laser class		
	Improved laser power (20mW) e.g. for dark surfaces		

*Options can be combined

Model		LLT	26xx-25	26xx-50	26xx-100
z-axis (height)	Standard measuring range	Start of measuring range	53.5mm	70mm	190mm
		Midrange	66mm	95mm	240mm
		End of measuring range	78.5mm	120mm	290mm
		Height of measuring range	25mm	50mm	100mm
	Extended measuring range	Start of measuring range	53mm	65mm	125mm
		End of measuring range	79mm	125mm	390mm
	Linearity ¹⁾	(2sigma)	±0.10% FSO	±0.10% FSO	±0.13% FSO
	Reference resolution ^{2) 3)}		2µm	4µm	12µm
x-axis (width)	Standard measuring range	Start of measuring range	23.4mm	42mm	83.1mm
		Midrange	25mm	50mm	100mm
		End of measuring range	29.1mm	58mm	120.8mm
	Extended measuring range	Start of measuring range	23.2mm	40mm	58.5mm
		End of measuring range	29.3mm	60mm	143.5mm
	Resolution x-axis		640 points/profile		
	Profile frequency	COMPACT / SMART / GAP	up to 300Hz		
		HIGHSPEED	up to 4,000Hz		
Interfaces	Multi function port	Ethernet GigE Vision	Output of measurement values Sensor control Profile data transmission		
		Digital inputs	Mode switching Encoder Trigger		
		RS422 (half-duplex) ⁴⁾	Output of measurement values Sensor control Trigger Synchronisation		
Output of measurement values		Ethernet (UDP / Modbus TCP); RS422 (ASCII / Modbus RTU) Analog ⁵⁾ ; Switch signal ⁵⁾ PROFINET ⁶⁾ ; EtherCAT ⁶⁾ ; EtherNet/IP ⁶⁾			
Display (LED)		1x laser ON/OFF, 1x power/error/status			
Light source		Semiconductor laser 658nm (red)			
Aperture angle laser line		20°	25°	25°	
Laser power	standard	≤ 8mW (2M laser class)			
	optional	≤ 20mw (3B laser class)			
Integrated laser switch-off	optional	Safety interlock, hardware switch-off			
Permissible ambient light (fluorescent light) ²⁾		10,000lx			
Protection class (sensor)		IP 65			
EMC		acc. EN 61326-1: 2006-10 DIN EN 55011: 2007-11 (group 1, B class) EN 61000-6-2: 2006-03			
Vibration		2g / 20 ... 500Hz			
Shock		15g / 6ms			
Operating temperature		0°C to 45°C			
Storage temperature		-20°C to 70°C			
Dimensions		96 x 85 x 33mm			
Weight sensor (without cable)		380g			
Supply		11-30VDC, 24V, 500mA, IEEE 802.3af class 2, Power over Ethernet			

¹⁾ Standard measuring range

²⁾ Measuring object: Micro-Epsilon standard object (metallic, diffusely reflecting material)

³⁾ According to a one-time averaging across the measuring field (640 points)

⁴⁾ RS422 interface, programmable either as serial interface or input for triggering / synchronisation

⁵⁾ Only with Output Unit

⁶⁾ Only with scanCONTROL Gateway

FSO = Full scale output



- z-axis measuring range up to 265mm
- x-axis measuring range up to 143.5mm
- Profile frequency up to 2,000Hz
- Measuring rate up to 2,560,000 points/sec
- z-axis reference resolution from 1µm
- Resolution x-axis up to 1,280 points
- Also available with blue laser

Compact design for precise measurement tasks

The design of the LLT29xx series is focussed on minimal size and low weight. The controller is integrated in the housing, simplifying cabling arrangements and mechanical integration. Due to its compact design and the high profile resolution, the 29xx series is especially suitable for static, dynamic and robotic applications.

Interfaces for universal integration

The multi-function port can be used for power supply, as data output, for switching parameters, as trigger input or for synchronizing several scanCONTROL sensors. During synchronous operation, an integrated mode can be used to operate the sensors alternately compensating for overlapping laser lines.

One scanner is measuring whilst the other laser line is switched off. The scanners can be supplied via Ethernet if necessary. If Industrial Ethernet is used as data output, only one cable will remain that connects the sensor to the periphery.

Article description structure

LLT	29	00	-25	/SI
Options /SI = integrated laser switch-off /PT = integrated pigtail cable 0.25 m /3B = 3B laser class /BL = Blue Laser (blue-violet laser line)				
Measuring range 10mm (only Blue Laser) 25mm 50mm 100mm				
Class 00=COMPACT 10=SMART 11=GAP 50=HIGHSPEED				
Series LLT29xx				

For all SMART and GAP class sensors, the measurement data output can be carried out in different ways, e.g. via Ethernet UDP, Modbus TCP or serial. Micro-Epsilon converters enable data transmission via analog signals, digital switching signals, PROFINET, EtherNet/IP or EtherCAT.

Also available with blue laser

The Blue Laser technology uses a laser diode with a shorter wavelength of 405nm. The outstanding characteristics of this wavelength range enable reliable measurements to be made that to date have been difficult to achieve using red laser scanners. Its advantages can be seen particularly well on red-hot glowing metals, (semi-) transparent and organic materials.

Short measuring range

The laser line of only 10mm enables to reliably detect smallest details. The high profile resolution combined with the blue laser line allow for maximum precision destined for versatile applications, e.g. in the electronics production.

Options*

/SI	Integrated laser switch-off	/PT	Pigtail cable
	Hardware switch-off of the laser line		0.25m long cable directly out of the sensor
	/3B 3B laser class		/BL Blue laser line
	Improved laser power (20mW) e.g. for dark surfaces		Blue laser line (405nm) for (semi-) transparent, red-hot glowing and organic materials

*Options can be combined

Accessories from page 18

Model		LLT	29xx-10/BL	29xx-25	29xx-50	29xx-100
z-axis (height)	Standard measuring range	Start of measuring range	52.5mm	53.5mm	70mm	190mm
		Midrange	56.5mm	66mm	95mm	240mm
		End of measuring range	60.5mm	78.5mm	120mm	290mm
		Height of measuring range	8mm	25mm	50mm	100mm
	Extended measuring range	Start of measuring range	-	53mm	65mm	125mm
		End of measuring range	-	79mm	125mm	390mm
	Linearity ¹⁾	(2sigma)	±0.17% FSO	±0.10% FSO	±0.10% FSO	±0.10% FSO
	Reference resolution ^{2) 3)}		1µm	2µm	4µm	12µm
x-axis (width)	Standard measuring range	Start of measuring range	9.4mm	23.4mm	42mm	83.1mm
		Midrange	10mm	25mm	50mm	100mm
		End of measuring range	10.7mm	29.1mm	58mm	120.8mm
	Extended measuring range	Start of measuring range	-	23.2mm	40mm	58.5mm
		End of measuring range	-	29.3mm	60mm	143.5mm
	Resolution x-axis		1,280 points/profile			
Profile frequency	COMPACT / SMART / GAP	up to 300Hz				
	HIGHSPEED	up to 2,000Hz				
Interfaces	Multi function port	Ethernet GigE-Vision	Output of measurement values Sensor control Profile data transmission			
		Digital inputs	Mode switching Encoder Trigger			
		RS422 (half-duplex) ⁴⁾	Output of measurement values Sensor control Trigger Synchronisation			
Output of measurement values		Ethernet (UDP / Modbus TCP); RS422 (ASCII / Modbus RTU) Analog ⁵⁾ ; Switch signal ⁵⁾ PROFINET ⁶⁾ ; EtherCAT ⁶⁾ ; EtherNet/IP ⁶⁾				
Display (LED)		1x laser ON/OFF, 1x power/error/status				
Light source	standard	Semiconductor laser 405nm (blue)	Semiconductor laser 658nm (red)			
	optional	-	Semiconductor laser 405nm (blue)			
Aperture angle laser line		10°	20°	25°	25°	
Laser power	standard	≤ 8mW (2M laser class)				
	optional	-	≤ 20mw (3B laser class)			
Integrated laser switch-off	optional	Safety interlock, hardware switch-off				
Permissible ambient light (fluorescent light) ²⁾		10,000lx				
Protection class (sensor)		IP 65				
EMC		acc. EN 61326-1: 2006-10 DIN EN 55011: 2007-11 (group 1, B class) EN 61000-6-2: 2006-03				
Vibration		2g / 20 ... 500Hz				
Shock		15g / 6ms				
Operating temperature		0°C to 45°C				
Storage temperature		-20°C to 70°C				
Dimensions		96 x 118.5 x 33mm	96 x 85 x 33mm			
Weight sensor (without cable)		440g	380g			
Supply		11-30VDC, 24V, 500mA, IEEE 802.3af class 2, Power over Ethernet				

¹⁾ Standard measuring range

²⁾ Measuring object: Micro-Epsilon standard object (metallic, diffusely reflecting material)

³⁾ According to a one-time averaging across the measuring field (640 points)

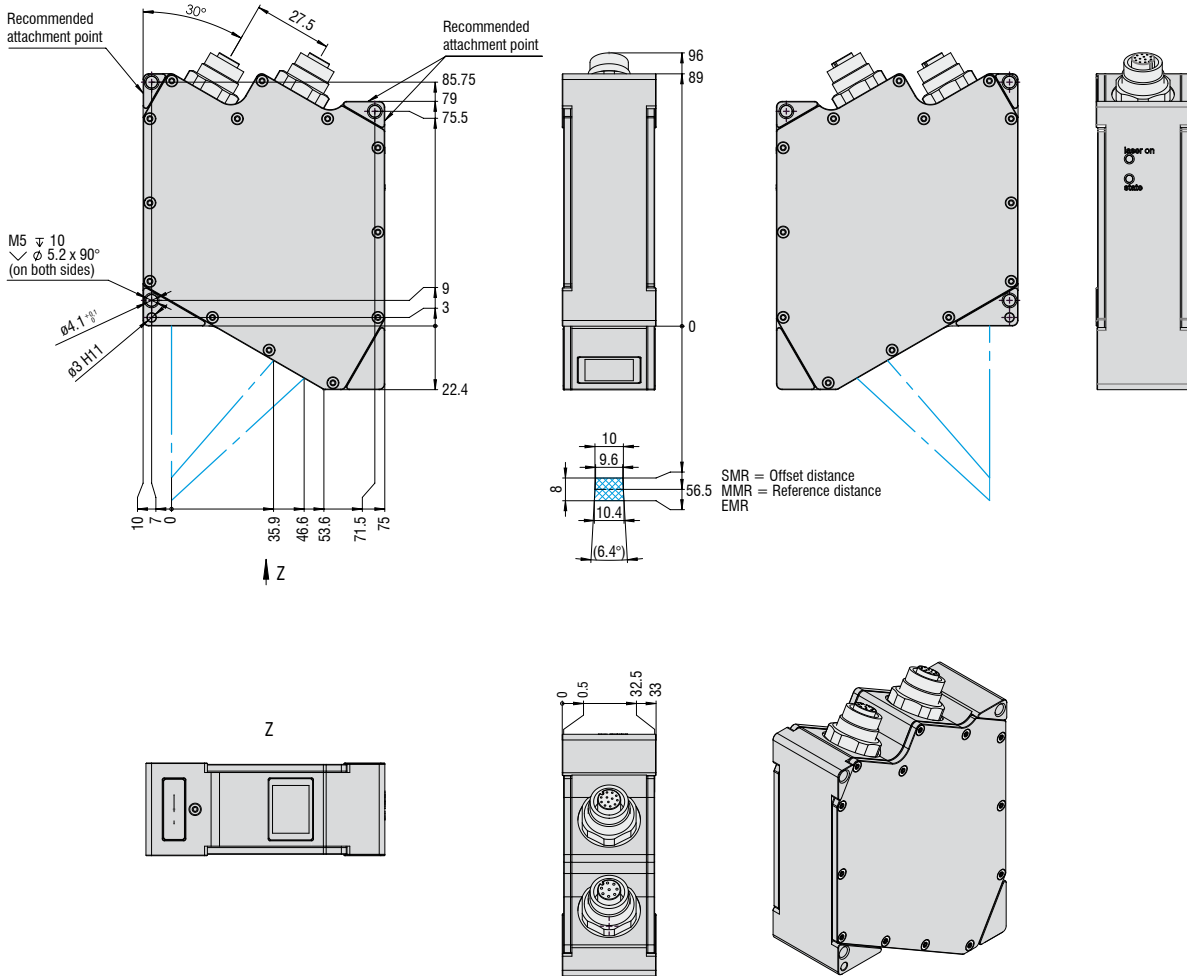
⁴⁾ RS422 interface, programmable either as serial interface or input for triggering / synchronisation

⁵⁾ Only with Output Unit

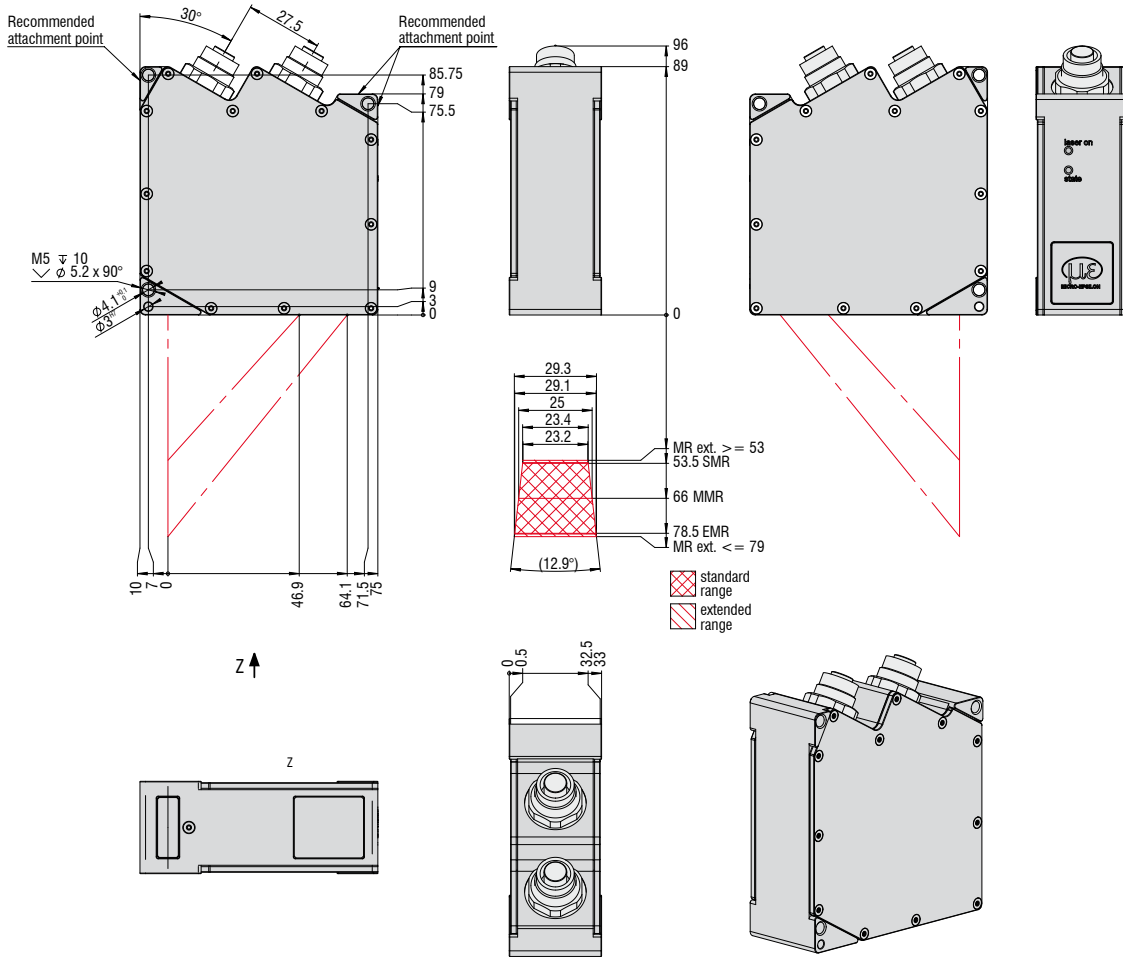
⁶⁾ Only with scanCONTROL Gateway

FSO = Full scale output

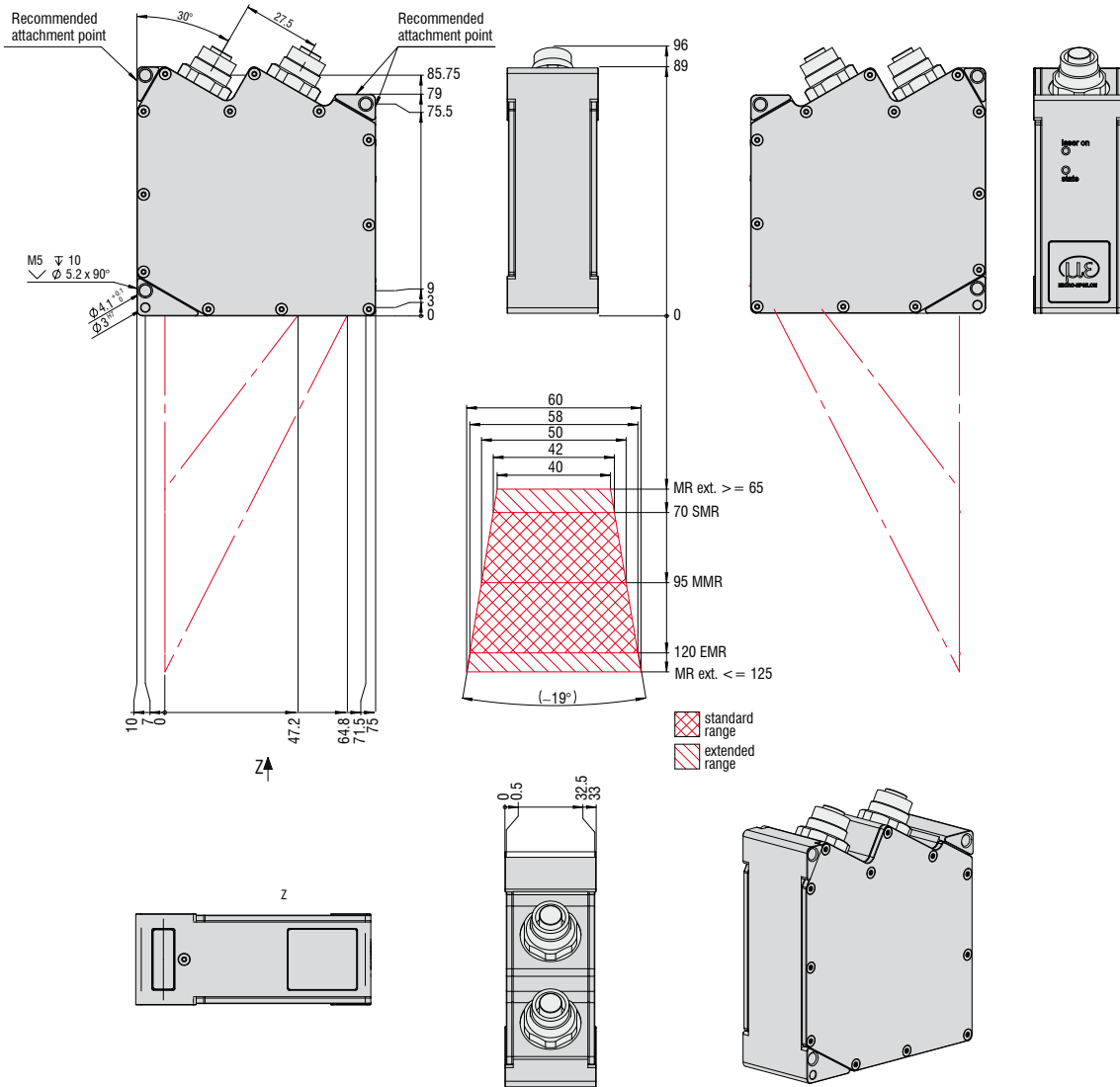
LLT29xx-10/BL



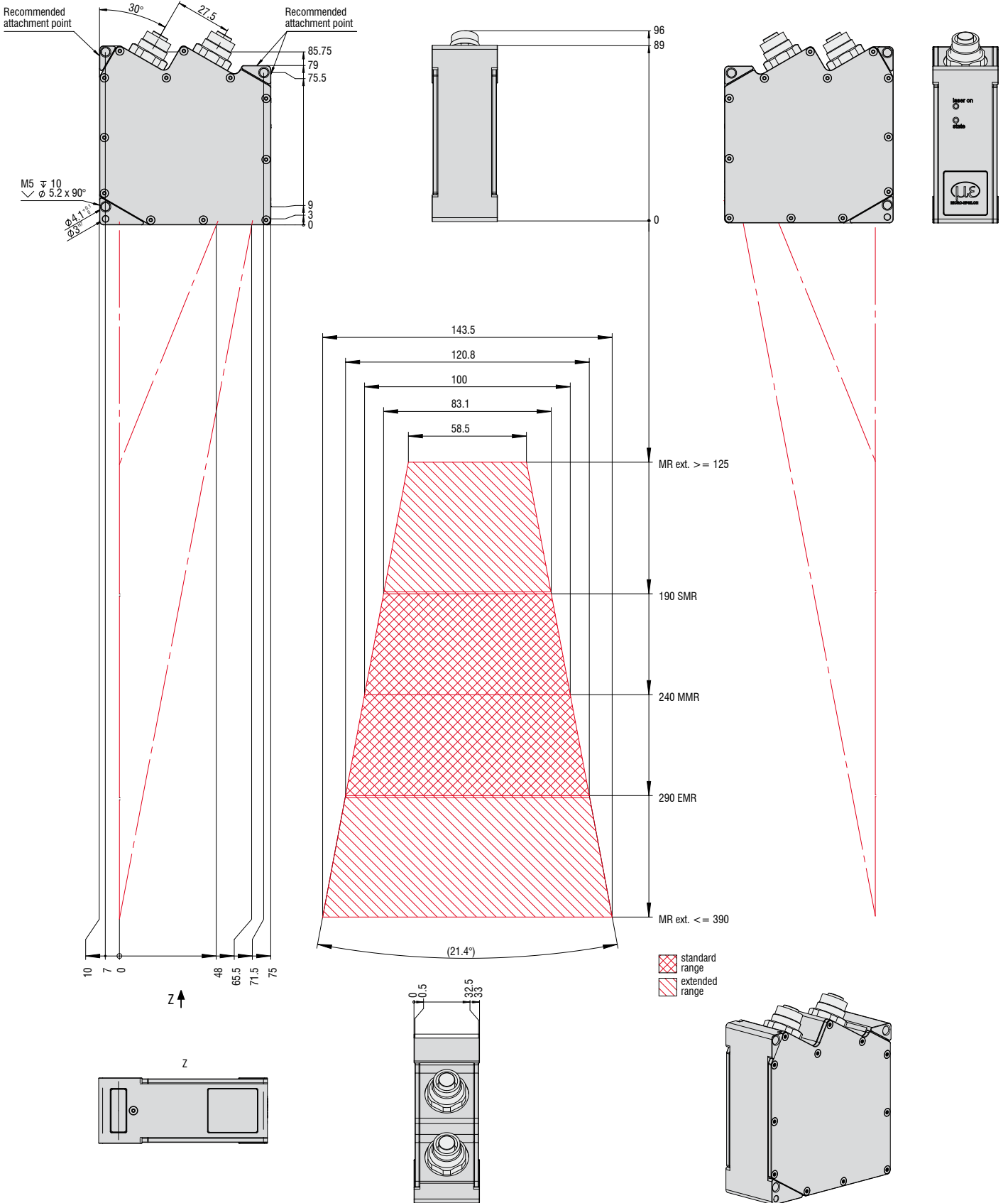
LLT26xx/29xx-25



LLT26xx/29xx-50



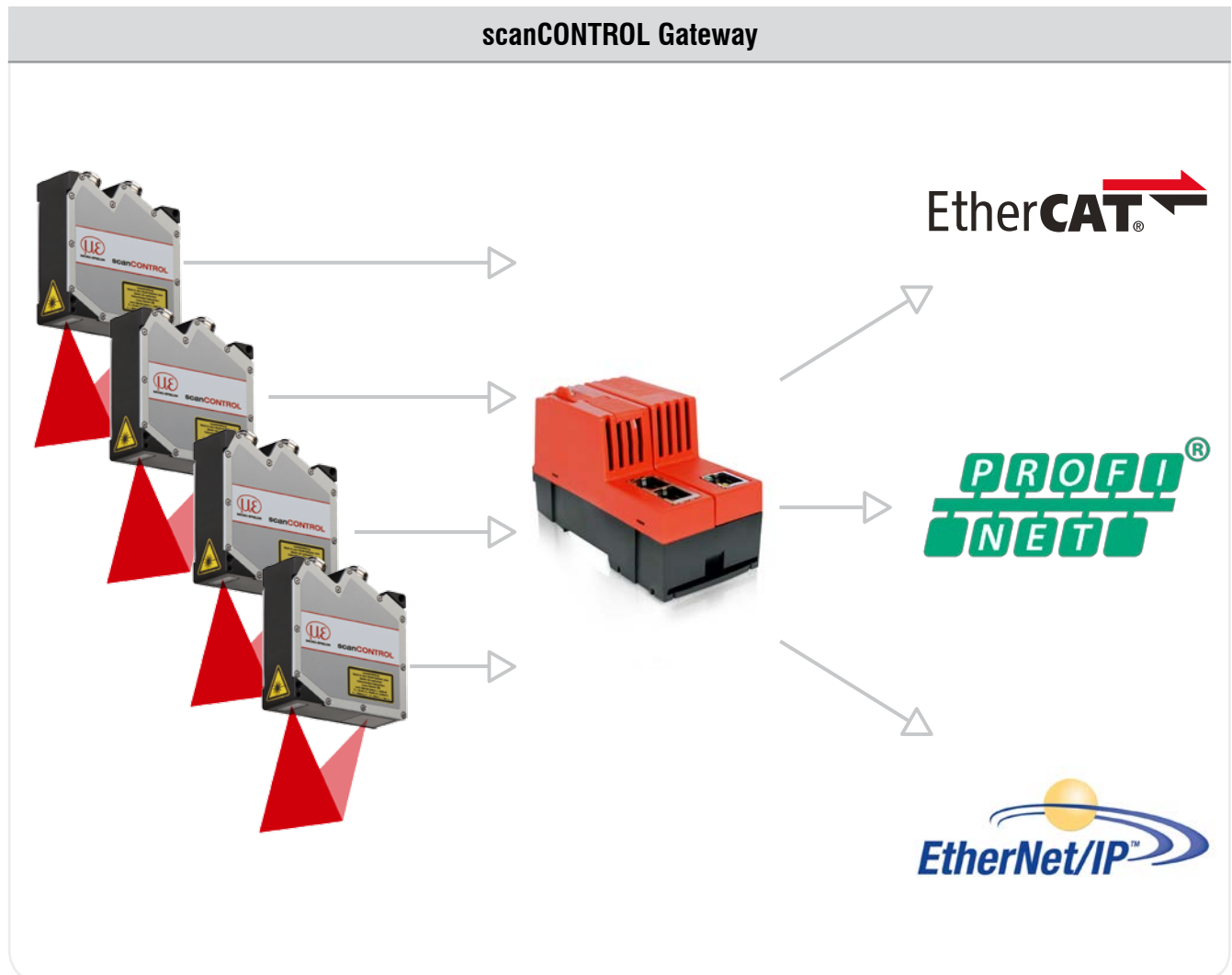
LLT26xx/29xx-100



PROFINET / EtherCAT / EtherNet/IP – for all scanners of the SMART and GAP classes

Each scanCONTROL Gateway can be connected with up to 4 sensors. It communicates with the scanCONTROL SMART sensor or the gapCONTROL sensor via Ethernet Modbus. The resultant values are then converted to PROFINET, EtherCAT or EtherNet/IP. The customer carries out the parameter set up with a detailed instruction manual.

*operating more than one sensor requires a switch.

**Gateway**

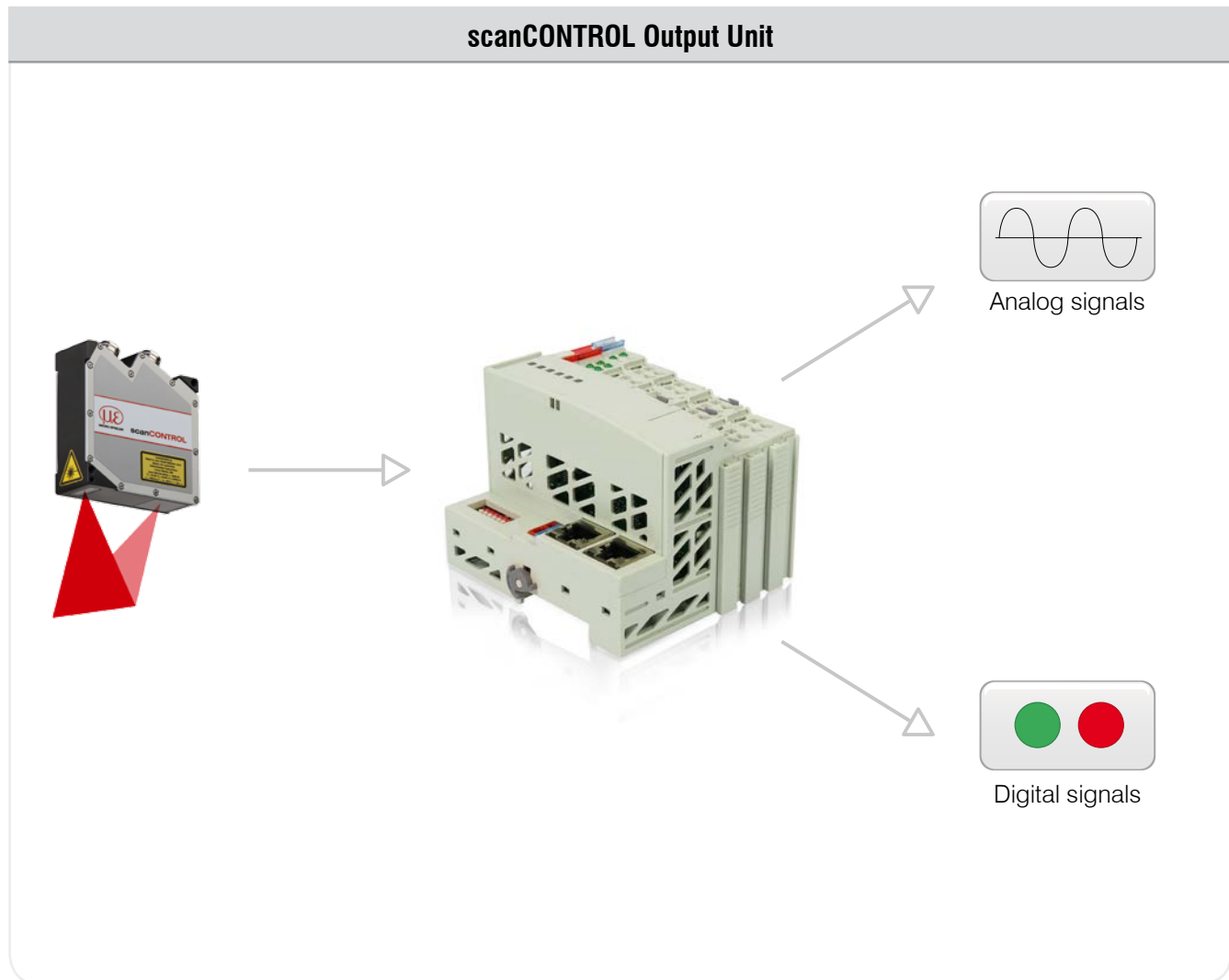
6414129	scanCONTROL Gateway
6411168	scanCONTROL SPU Switch, 5 ports
6411167	scanCONTROL SPU Switch, 8 ports

Fieldbus coupler, configurable for PROFINET, EtherNet/IP and EtherCAT
 Industrial Ethernet Switch (unmanaged) for mounting rail, 10/100/1000 Mbit/s, 5 ports
 Industrial Ethernet Switch (unmanaged) for mounting rail, 10/100/1000 Mbit/s, 8 ports

Sensors on the gateway	Max. measurement frequency
1	450Hz
2	240Hz
3	160Hz
4	120Hz

Analog signals / digital switching signals – for all scanners of the SMART and GAP classes

The scanCONTROL Output Unit is addressed via Ethernet and outputs analog and digital signals. Different output terminals can be connected to the fieldbus coupler.

**Output Unit**

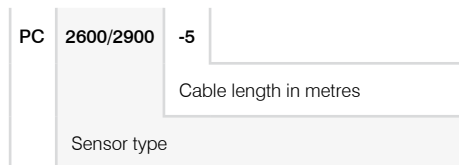
6414073	Output Unit Basic/ET	Fieldbus coupler with filter module and bus end terminal
0325131	OU-DigitalOut/8-channel/DC24V/0.5A/negative	8-channel digital output terminal; DC 24V; 0.5A; negative switching;
0325115	OU-DigitalOut/8-channel/DC24V/0.5A/positive	8-channel digital output terminal; DC 24V; 0.5A; positive switching
0325116	OU-AnalogOut/4-channel/±10V	4-channel analog output terminal; ±10V
0325135	OU-AnalogOut/4-channel/0-10V	4-channel analog output terminal; 0-10V
0325132	OU-AnalogOut/4-channel/0-20mA	4-channel analog output terminal; 0-20mA
0325133	OU-AnalogOut/4-channel/4-20mA	4-channel analog output terminal; 4-20mA

Further terminals are available on request.

Connection cable

Multi-function cable

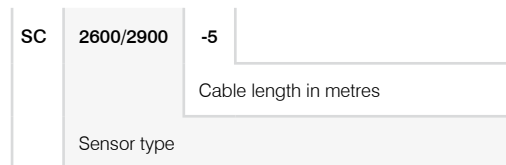
For power supply, digital inputs (TTL or HTL), RS422 (half-duplex)



PC = Multi-function cable qualified for drag chain use
PCR = Multi-function cable suitable for use with robots

Ethernet connection cable

For parameter set up, value and profile transmission



SC = Ethernet connection cable qualified for drag chain use
SCR = Ethernet connection cable suitable for use with robots

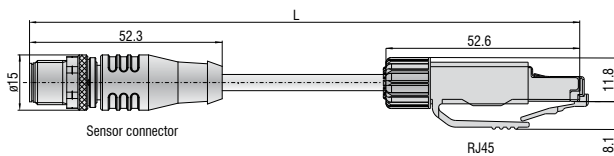
Accessories

Art. No. Model

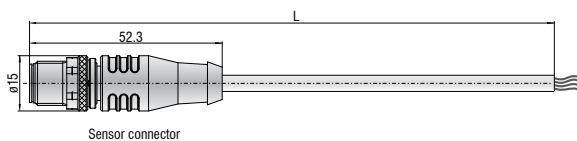
0323478 Connector/12-pol/LLT2600-2900/PS/RS422/DigIN
0323479 Connector/8-pol/LLT2600-2900/Ethernet
2420067 PS2600/2900
0254072 Suitcase scanCONTROL 26/27/29 MR 10-100

Description

Connector multi-function port for scanCONTROL series LLT26xx and 29xx
Connector for Ethernet socket for scanCONTROL series LLT26xx and 29xx
Power supply unit for scanCONTROL 2600/2900
Transport suitcase for scanCONTROL sensors, incl. measuring stand



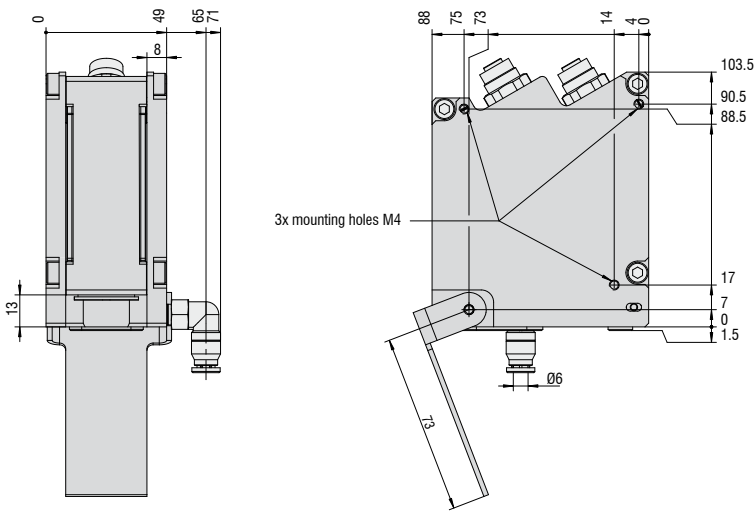
Ethernet connection cable



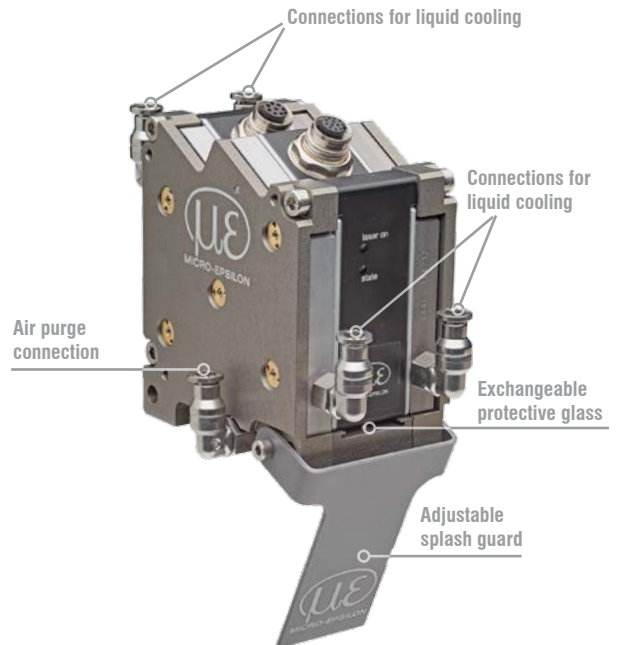
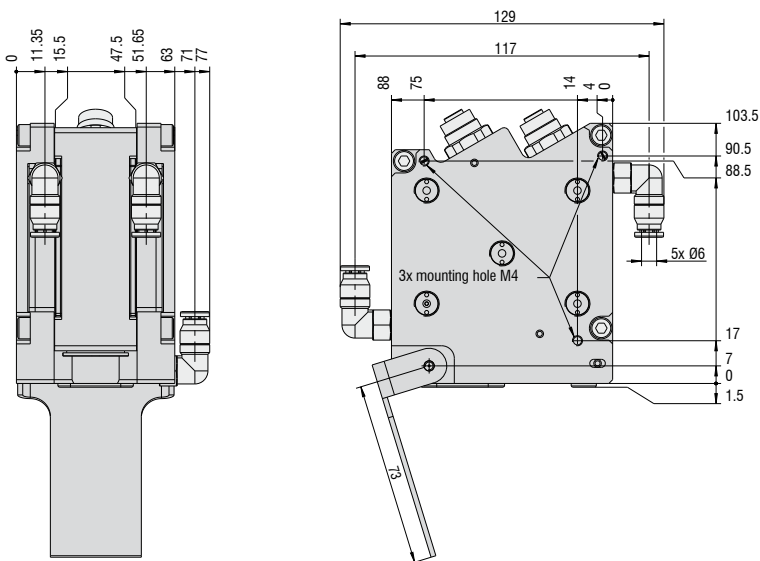
Multi-function cable

Protection and cooling housing for LLT26xx and 29xx

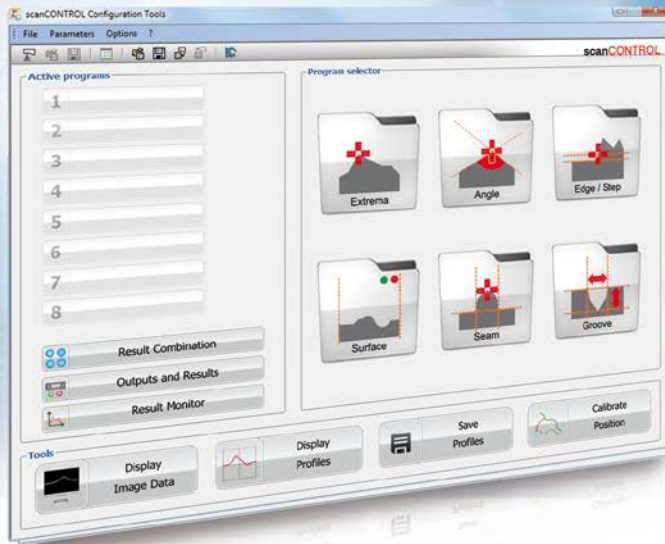
Protection housing including blow-out system



Protection housing including blow-out system and water cooling



Art. No.	Model	Description
2105058	scanCONTROL LLT26/29 protection housing	Adaptive protection housing for scanCONTROL 26xx/29xx
2105059	Protective scanCONTROL LLT26/29 cooling housing	Adaptive protection and cooling housing for scanCONTROL 26xx/29xx
0755075	Exchangeable glass for protection housing	Exchangeable glass for protection/cooling concept LLT 26/29, pack. with 50 pcs



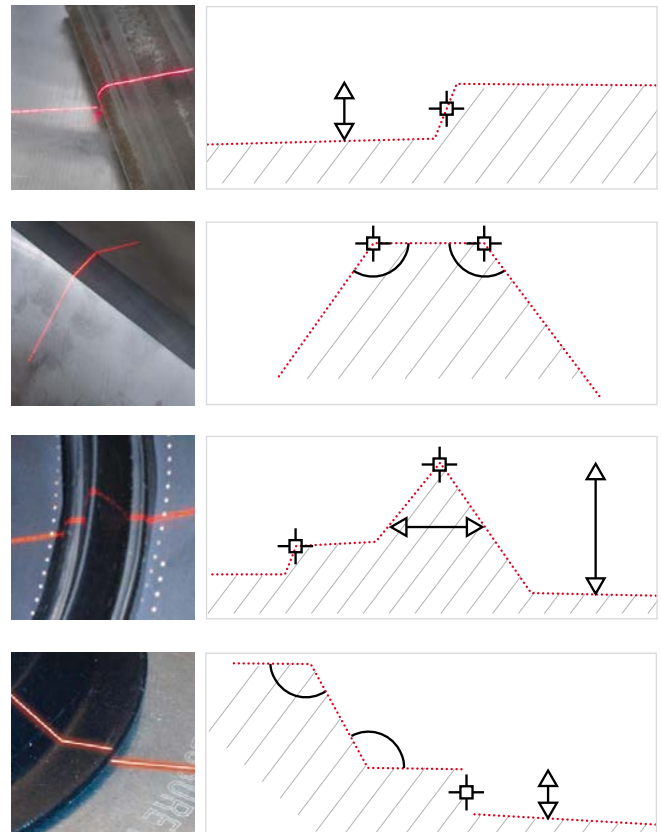
- Plug & Play solution for complex measurement tasks
- Evaluation in the sensor head - without external controller
- Parallel execution of different measurement tasks and multiple evaluation
- Easy online and offline analysis

The sensors of the SMART series have an intelligent controller which allows simple profile analysis without an additional PC.

The scanCONTROL Configuration Tools software is used for parameter set up of the profile analysis. As well as configuration of the sensor, this also enables the parameters of the measurement task to be set up and of the outputs, resulting in a compact, industrial, inline measurement solution.

For offline testing of high speed processes, the functions of the software also operate using pre-recorded profiles, without requiring a sensor to be connected.

A complete profile analysis task can be programmed in four simple steps. The pre-configured measuring system operates in standalone mode and transmits the measured values to a PLC.



The system is freely configurable and can be quickly and easily adjusted for a variety of tasks

Step 1**Alignment of the sensor**

The 'Display Image Data' module will help you to mount the sensor. This shows a live image of the sensor matrix and the optimum measuring range, as well as the reflection characteristics of the target.

Step 2**Sensor setting**

Selecting exposure time, profile frequency and other parameters adjust the laser scanner to the desired application. Dynamic algorithms such as the automatic exposure time or the dynamic threshold enable to detect difficult surfaces as well. The software delivers a direct feedback about the achieved saturation and the current scanner profile frequency.

Step 3**Selection of measurement programs**

Depending on the measurement task, one or more measurement programs can be selected with a simple mouse click. More than 25 modules are available. There are different module groups for the respective, common profile measurement tasks. The measurement programs to the right are suitable for the exemplary profiles above.

Step 4**Configuration of measurement programs**

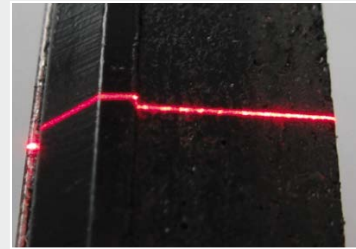
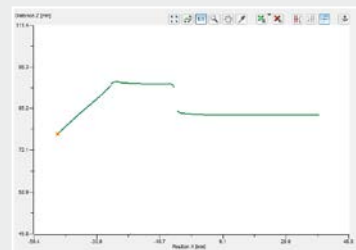
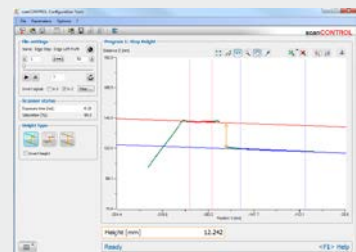
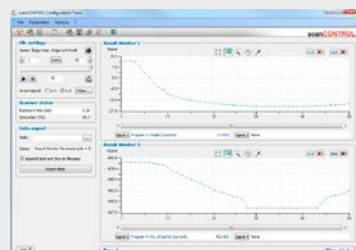
Each of these measurement programs can be individually configured. On a simple interface, different methods of interacting with the live measurement signal are available. Therefore, the relevant areas of the signal, for example, can be cut out and reference points set. The results of the individual measurement packages are displayed directly in the profile.

Step 5**Defining the outputs and displaying measured values**

In the final step, all measurement values are displayed as a profile, filtered temporally if required, and assigned to the different outputs. Limit values and interfaces can therefore be easily configured.

Download:

<http://www.micro-epsilon.com/configuration-tools>

Step 1**Alignment of the sensor****Step 2****Sensor setting****Step 3****Selection of measurement programs****Step 4****Configuration of measurement programs****Step 5****Output and display of measured values**



- Plug & Play solution for gap measurements
- Different gap definitions
- Various measurement values (gap width, height offsets, position,...)
- Evaluation in the sensor head - without external controller

The following gap main groups are available:

Basic gaps

The edgeless gaps are the so-called „Basic Gaps“ and are characterised by clearly defined reference points for gap measurement. These could be, for example, the end points or the lowest points of each side. Furthermore, the offset of both sides is easily measurable. This gap type allows for an easy entry and the desired measurement result is output by modifying just a few settings.

Projected gaps

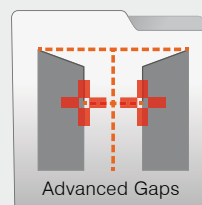
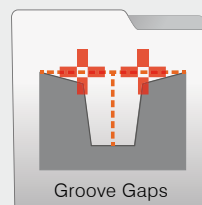
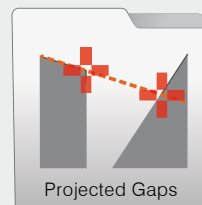
With these types of gaps, the end points of both sides are projected. There are different ways of projection, for example, the projection onto a common parallel or the projection of an end point onto the opposite side. The distance between the projected points is described as gap width. The pre-defined gap variants allow for easy and fast setting.

Groove gaps

If there is a visible ground in the gap, further inspections can be carried out in order to e.g. measure the gap depth. The evaluations also apply for grooves and other cavities. With soldering applications e.g. the so-called V-gap of pipelines, special algorithms of the „Advanced Groove Gap“ output the oscillation width depending on the current soldering depth.

Advanced gaps

These types offer the user advanced settings. The algorithms for flushness measurement or projection can be adapted independently of each other as well as the search criteria for the respective gap points. Furthermore, these gap types provide numerous additional measured values such as angle or unevenness of the edges.



Main groups of different gap types

gapCONTROL Setup Software

Not all gaps are alike. There are different definitions of how the optical gap is defined for different industries and measuring targets. The gapCONTROL Setup Software enables quick and easy configuration of gapCONTROL sensors. Both components together represent a complete solution for automated gap measurement. After parameterisation, the sensor operates in standalone mode. However, the software can be used for the visualisation of the measured values.

gapCONTROL modes

The user-friendly, intuitive software guides the user through the program. In the first step, a gap mode is chosen from a wide selection of conventional gap types. This pre-selection specifies a start configuration for the chosen gap type. With simple types of gap, e.g. "Edge Points Gap", no additional configuration is needed. Other gap types offer application-specific configuration options.

Set up and configuration of gap measurements

After selecting the gap mode, the search algorithms for the right and left-hand gap edges as well as for the gap offset are specified with the gapCONTROL Software. For dynamic processes, gapCONTROL also offers tracking functionality, e.g. following the centre position.

Measurement output: plug & play solution in the integrated controller

For output of measured values, these can be configured with freely assigned values. The configuration of gapCONTROL can be saved in the memory of the sensor. Consequently, the sensor is ready for running in its standalone mode without an external PC. Besides measurement value output via Ethernet (Modbus TCP, UDP) and RS422 (Modbus RTU or ASCII format), additional digital switch signals and analog measuring values can also be output.

Measurement and evaluation of the measurement value sequence

Using the „Result Monitor“ analysis program, selected measurement value sequences of recorded profiles and live profiles can be displayed and analysed, enabling the evaluation of measurements. Additionally, an integrated cgm analysis (capability gauge measurement), and further statistical parameters (e.g. limit value exceeded, average values) are available. The software allows these values to be exported for archive purposes or for further analysis in calculation tables.

Load and save

The gapCONTROL Setup Software allows both profiles and measuring results (e.g. gap width) to be saved. Stored profiles, even without a gapCONTROL sensor connected, can be re-loaded, and all parameters of the evaluation can be tested on these offline data. Several example profiles are already included with the standard installation of the gapCONTROL Setup Software, and they can largely be used to test the functioning of the software.

Download:

<http://www.micro-epsilon.com/gapcontrol-setup-software>

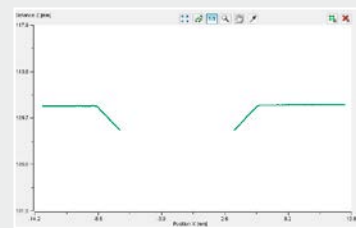
Step 1

Alignment of the sensor



Step 2

Sensor setting



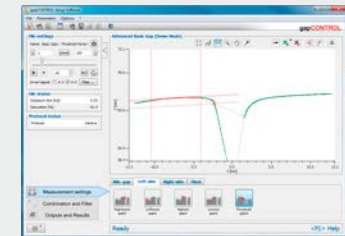
Step 3

Selection of measurement programs



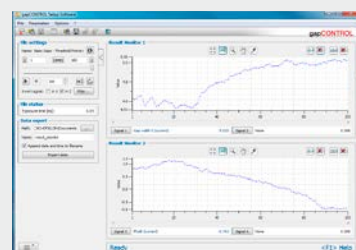
Step 4

Configuration of measurement programs



Step 5

Output and display of measured values





- Display of profile sequences
- Offline or real-time display of 3D profiles
- Synchronisation of the direction of travel (e.g. by encoder)
- 2D Export of the profile sequences (PNG)
- 3D Export (ASC, STL, CSV) for CAD programmes
- Intensity per point can be displayed and exported

3D visualisation for all scanCONTROL/gapCONTROL models

By means of the relative movement between sensor and target, the third dimension for the measurement data is obtained. The y-coordinates are assigned via a trigger or CMM counter.

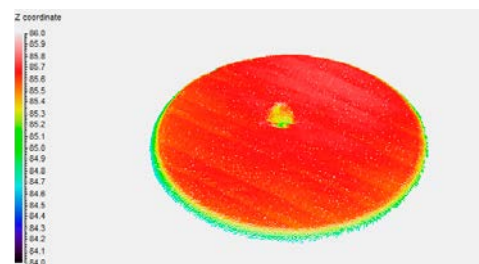
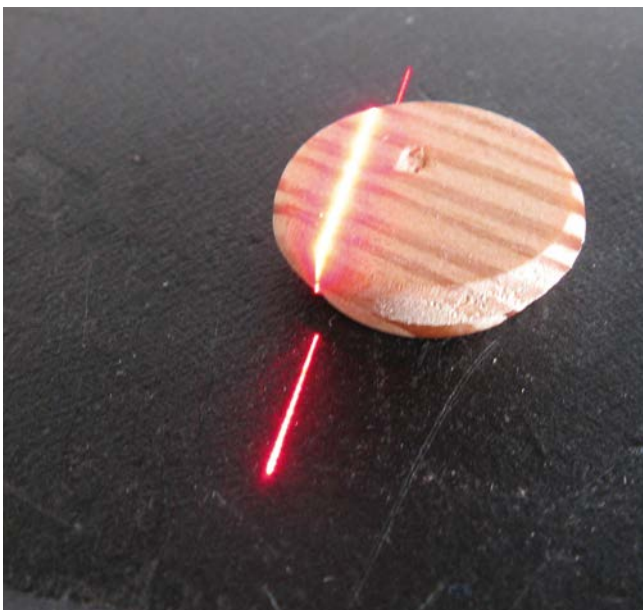
The scanCONTROL 3D-View software is designed for viewing and exporting this 3D data. In addition, 3D-View also supports the configuration of the sensor.

The software enables the interactive viewing of 3D data and the export of this measurement data to common data formats (ASCII, STL or PNG). Various display modes, views and color palettes help in setting up the sensors and analysing the profiles.

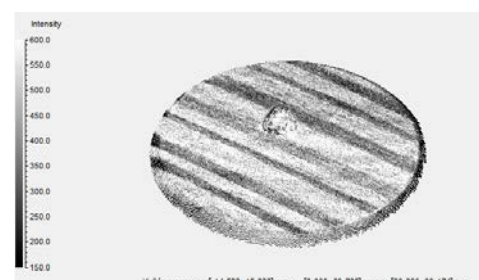
The software supports the online visualisation of the profiles as well as offline analysis of stored profile sequences.

Download:

<http://www.micro-epsilon.com/3d-view>

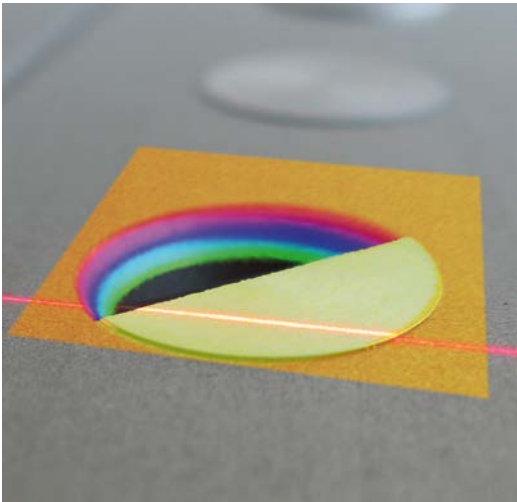


Distance profile

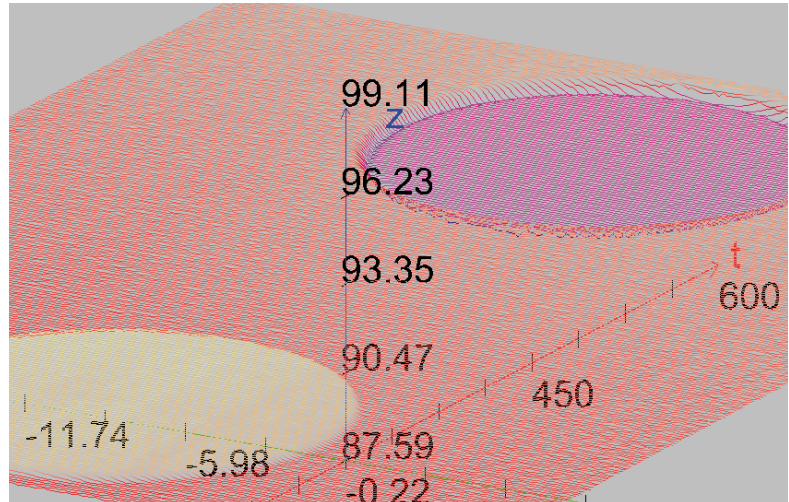


Intensity

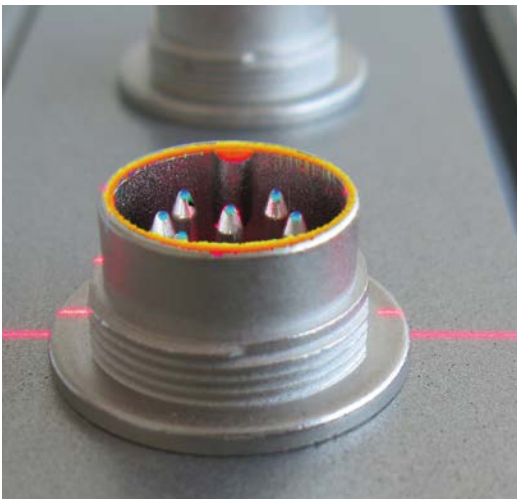
Visible range: x: [-14.523; 15.323] mm; y: [0.000; 39.735] mm; z: [80.226; 90.174] mm



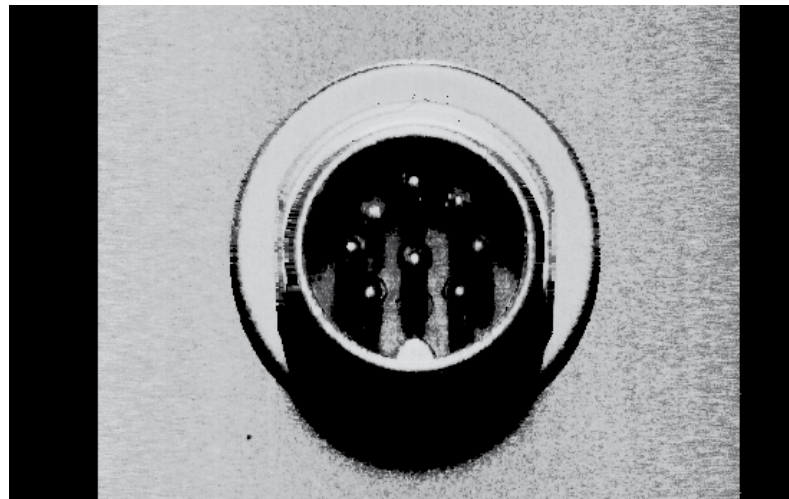
Rivet



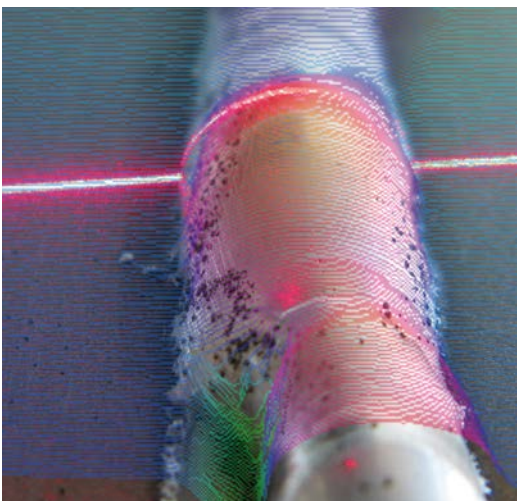
Display mode: „3D view lines“; Color palette „z-coordinates“



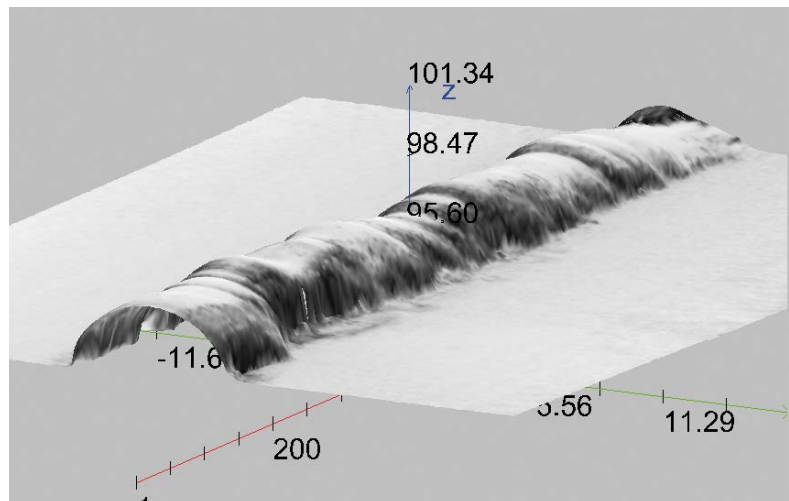
Pin



Display mode: „2D view“; Color palette „intensity“



Weld seam



Display mode: „3D view triangles“; Color palette coding "intensity"



The scanCONTROL COMPACT and HIGH SPEED sensors record a profile from individual calibrated points for each measurement. These profiles can be used individually or combined in a container set, and transferred to customer applications as an array or matrix. In addition to the data transfer of individual measuring points and their additional information (e.g. intensity, counter reading) the entire configuration of the sensor can also be controlled from its own application software.

Micro-Epsilon provides a number of interfaces to access the parameter and data transfer functions. The transmission interface primarily used by LLT sensors for communications and profile transfer is Ethernet.

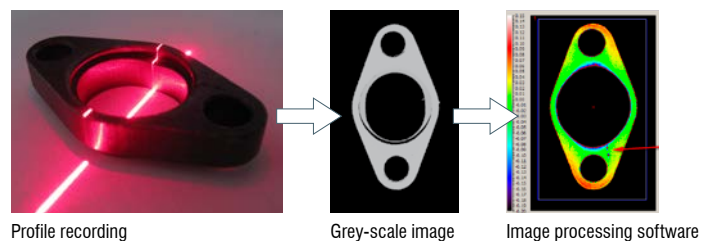
Ethernet and GigE Vision

Each scanCONTROL sensor complies with the GigE Vision Standard (Gigabit Ethernet for Machine Vision) of the AIA (Automated Imaging Association).

The standard is widely used in the image processing industry and is therefore supported by all conventional computer vision tools, ensuring fast and smooth integration into different image processing software packages - also for 3D evaluation.

GigE Vision ensures optimum data security, perfect performance and short design-in times during implementation. GigE Vision is based on gigabit Ethernet and offers a maximum transfer rate. Ethernet technology offers advantages such as long cable lengths without using repeaters/hubs, and it permits the use of inexpensive network components. The GigE Vision standard provides an open framework for data transmission (e.g. profiles, data sets) and control signals between scanCONTROL and a PC. The infrastructure topology provides numerous opportunities for single and multiple scanner applications.

GigE[®]
VISION



Profile recording

Grey-scale image

Image processing software

Integration with the C/C++ library

The C/C++ library for scanCONTROL supports both static and dynamic loading. Both stdcall and cdecl are supported as calling conventions. The individual functions of the library are clearly documented in the interface description and explained using examples.

The scanCONTROL SDK integration package includes:

- the LLT.DLL library file
- Interfaces and scanCONTROL documentation
- numerous programming examples for C++ and C#, e.g. for trigger and container mode
- Tool DeveloperDemo.exe for quick testing of the sensor configuration.

SetFeature ()

```
int
LLTI.SetFeature(uint pLLT, uint Function, uint Value);
```

Setzen des Parameters einer Eigenschaft.

Parameter	Device Handle
pLLT	Device Handle
Function	Registeradresse der Funktion (FEATURE)
Value	Zu schreibender Wert

Rückgabewert

Standard	Spezifisch
ERROR_SE	FEATURE
FEATURE	FEATURE

```
// Struct necessary for defining the partial profile
LLTI.PartialProfile PartialProfile;

double[] adValueX = new double[m_uResolution];
double[] adValueZ = new double[m_uResolution];
byte[] abyTimeStamp = new byte[16];

// Set the partial profile structure
PartialProfile.nStartPoint = 20; // Offset 20 -> start at the 21th point of the profile
PartialProfile.nStartPointData = 4; // Startpoint 4 bytes -> location of X and Z
PartialProfile.nPointCount = m_uResolution / 2; // transmit half the resolution
PartialProfile.nPointDataWidth = 4; // 4 bytes -> X and Z (2 bytes each)

// Allocate buffers
byte[] abyProfile = new byte[PartialProfile.nPointCount * PartialProfile.nPointDataWidth];

// Set the part
PartialProfile.nPointCount = m_nPointCount;

Console.WriteLine("SetFeature: uint PartialProfile.nPointDataWidth");
if ((RetValue = LLTI.SetFeature(pLLT, "PARTIALPROFILE", PartialProfile)) < LLTI.GENERAL_FUNCTION_OK)
{
    OnError("SetFeature: uint PartialProfile.nPointDataWidth");
    return false;
}
return true;
}
```

Integration with LabVIEW

The LabVIEW scanCONTROL instrument driver supports fast integration of scanCONTROL sensors into the LabVIEW application environment. For accessing a scanCONTROL sensor and its basic settings, users can drag-and-drop modules directly from the function palette into their VI. Example VIs that illustrate scanCONTROL integration are also included in this package.

The integration of scanCONTROL sensors into the LabVIEW environment is based on the C/C++ library (LLT.DLL) of Micro-Epsilon. Detailed documentation also shows how to set up additional special sensor parameters.

The image shows a LabVIEW VI for scanCONTROL. On the left is a control panel with fields for 'Sensor ID', 'Working Mode', 'Profile per profile', 'Resolution', 'Measuring field', 'Measuring field number', 'Shutter time', and 'Auto exposure'. In the center are two graphs: the top one shows a noisy profile with 'Profile (mm)' on the y-axis and 'Position (mm)' on the x-axis; the bottom one shows a smooth parabolic profile with the same axes. On the right is a block diagram with a palette of 'Instrument I/O' modules, including 'scanCONTROL_2xxx'. The main diagram shows a sequence of operations: 'scanCONTROL_2xxx' -> 'GetProfile' -> 'Profile to Array' -> 'Array to Profile' -> 'Profile to Graph'.

Integration with Linux

The integration into Linux is performed using an Open Source C library which has been extended by some important control features for scanCONTROL. An additional C++ library enables fast sensor integration of the entire functionality into a user-friendly API.

This library is based on the GeniCam standard which is why the sensor can be controlled either via GeniCam commands or directly via the control parameters listed in the documentation. For integration support (e.g. trigger, container mode), also some example programs are available.

Use on ARM embedded PCs (e.g. Raspberry Pi) is possible with restrictions.

The image shows a Linux interface for scanCONTROL. On the left is a control panel with fields for 'Resolution', 'Predefined measuring field', 'Measuring field number', 'Laser Power', 'Shutter time in ms', and 'Auto exposure'. In the center is a graph showing a triangular profile with 'F-Axis' on the y-axis and 'X-Axis' on the x-axis. On the right is a terminal window showing the following output:

```
pi@raspberrypi:~/Linux_scanCONTROL$ ./Linux_scanCONTROL
There are 2 scanCONTROL sensors
MICRO-EPSILON Optoedge Scan-2000000
MICRO-EPSILON Optoedge Scan-2000000
The scanCONTROL is a scanCONTROL
Register callbacks
Show getting profiles via GeniCam
Start acquisition of profiles
1: All profiles received: 10
X/Z extracted!
X: -26.91 Z: 84.1666
Profile Count: 82915 Successes: 100.00% Failures: 0
Disconnect
pi@raspberrypi:~/Linux_scanCONTROL$
```



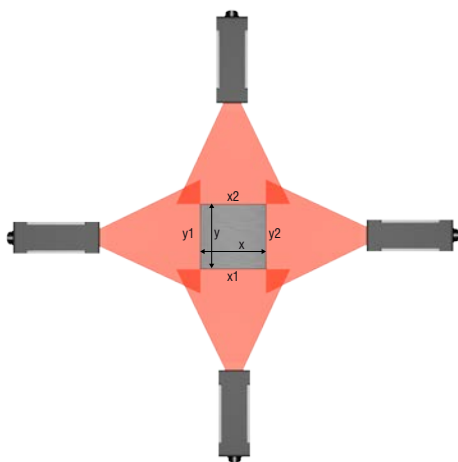
- Measurement value evaluation of up to 8 laser scanners
- Transmission of measured values to higher-level PLC (PROFINET, UDP, Modbus)
- Digital / analog in- / outputs
- Integrated web server for display of results
- Numerous possibilities for recording measurement values

Many applications require several scanners e.g. for contour measurement or when detecting large components. The scanCONTROL Smart PLC Unit is an industrial control unit incl. customised application software for measurement value calculation intended for laser scanners of the scanCONTROL Smart and gapCONTROL product classes.

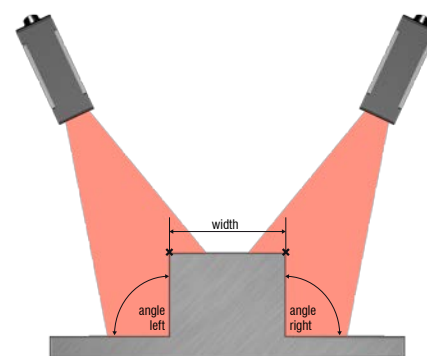
The scanned measurement values are evaluated, displayed, recorded and transmitted to higher-level PLCs using analog and digital interfaces. The modular design of the Smart PLC Unit enables the user to connect up to 8 laser scanners.

Application examples:

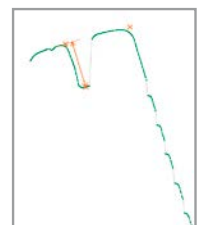
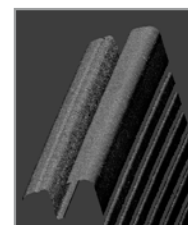
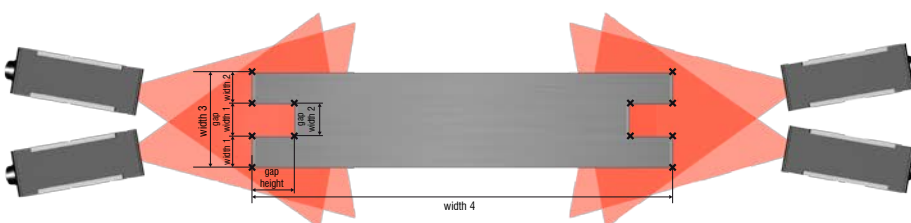
Determination of cross-section in the extrusion process

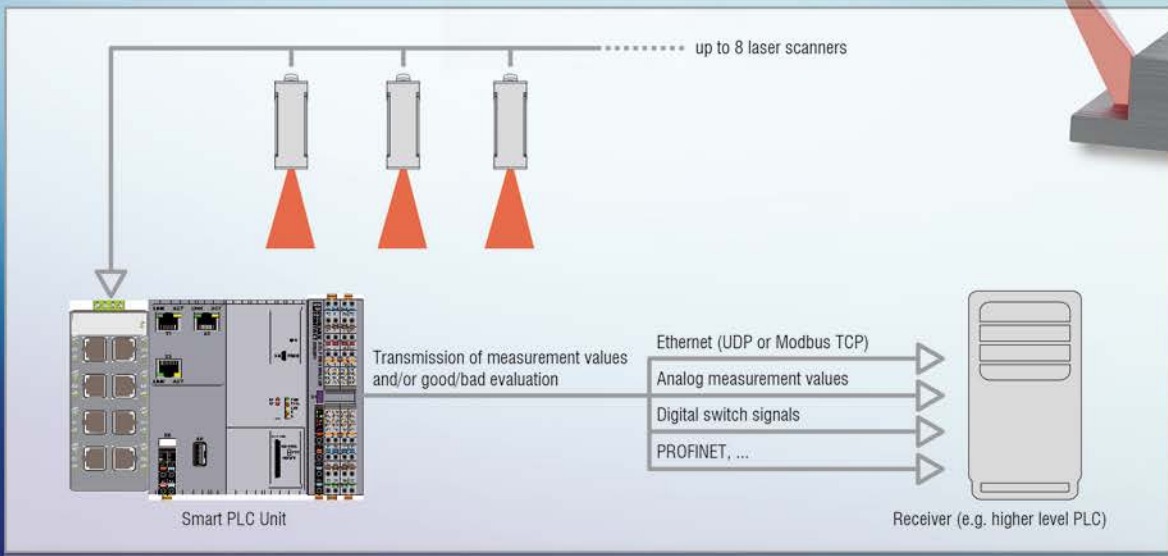


Contour measurement of a rail



Profile evaluation (profile width, bar width, groove width, groove depth)





High performance sensors made by Micro-Epsilon



Sensors and systems for displacement and position



Sensors and measurement devices for non-contact temperature measurement



2D/3D profile sensors (laser scanner)



Optical micrometers, fiber optic sensors and fiber optics



Color recognition sensors, LED analyzers and color online spectrometer



Measurement and inspection systems

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